

SURPAD 4.2 USER GUIDE

For Android Platform

V1.1

Shanghai eSurvey GNSS Co., Ltd.



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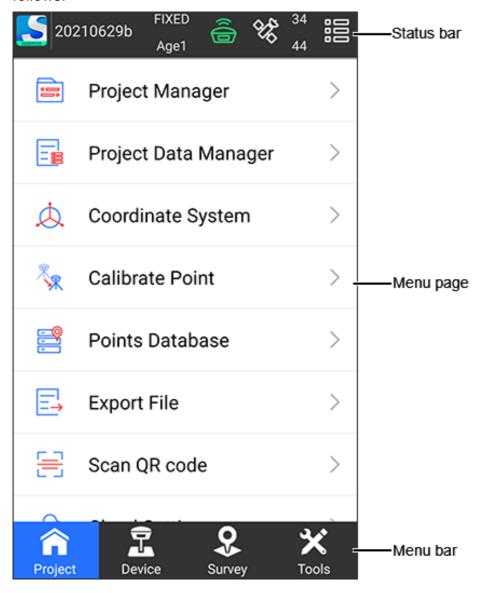
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1 SurPad at a Glance

Based on the Android platform, SurPad is a GNSS surveying and mapping software, developed by e-Survey. Combining with the international mainstream of surveying and mapping data acquisition function, it integrates RTK control, GIS data collection and road design and layout into one role.

With graphic interaction, SurPad is very powerful but easy-to-use. Its interface layout is as follows:





1.1 Status Bar

This part gives information about SurPad and the receiver:

Status icon		What it does
AADROID	About software	To submit your feedback about the software, activate the software, and update the software.
20210629b	Project name	To show the name of the current project.
FIXED Age1	Solution status and delay	To show the solution status (including single, float, differential and fixed) and the differential delay in real-time.
	Communicatio n	To show the connection status between the receiver and device. Green: connection succeeds. White: connection fails.
88	Positioning information	To check the current positioning information.
34 44	Satellites count	To show the used satellites number (e.g. 34) and the observed satellite number (e.g. 44).
	Main interface setting	To set the interface style to List or Grid , and set whether to enable general function, road function, electric function and other function which are enabled by default.

1.2 Menu Bar

This part gives access to the software functions:

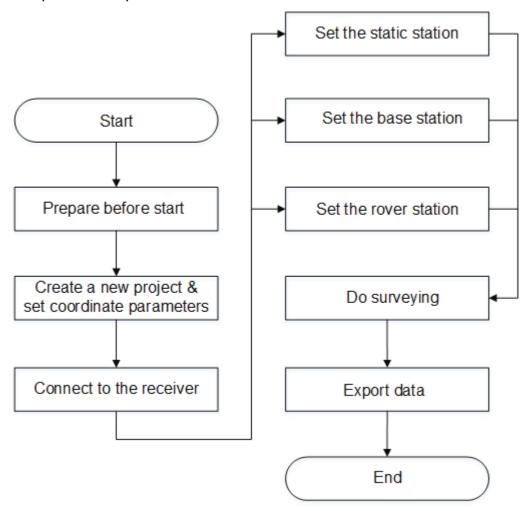
Menu		What it does
Project	Project menu	To manage project operations. See <u>3</u> Project for details.
Device	Device menu	To set operation mode and check information of the receiver after connecting to the receiver. See <u>4</u> Device for details.
Survey	Survey menu	To start your survey work. See <u>5</u> Survey for details.
Tools	Tools menu	To select various calculation methods. See <u>6</u> Tools for details.



2 Quick Start

To learn how to get your SurPad software up and running.

The process of quick start is as follows:





2.1 Prepare before Start

It is used to make sure that your SurPad can work and run normally.

To prepare before start, do the following:

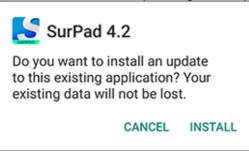
- 1. Prepare the following:
 - Two GNSS receivers (one base station and one rover station)
 - o An Android device with network connected.
- 2. Install the SurPad.
- 3. Activate the SurPad.

2.1.1 Install the SurPad

It is used to make sure the SurPad can be correctly installed in your Android device.

To install the SurPad, do the following:

- 1. Download the Android SurPad installation package (*.apk), and copy it to an Android device.
- 2. Find the installation package in **File Manager** in Android device.
- 3. Press the installation package, and press **INSTALL** in the following prompt:



- 4. After a prompt *App installed* shows, press one of the following:
 - o **DONE**: to return to the path where the installation packages puts.
 - o **OPEN**: to open SurPad software.

After installing the SurPad, to uninstall it, do one of the following:

- Long press the software icon on the desktop and drag it to **Uninstall** box.
- Press Settings → APPs, find SurPad, and press SurPad and Uninstall.



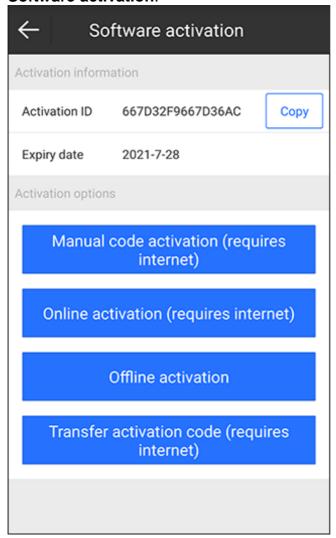
2.1.2 Activate the SurPad

When you start SurPad at the first time, registering your license of the software is required. Otherwise, you cannot use SurPad normally.

To activate the SurPad, do the following:

1. To enter **Software Activation** interface, in the status bar, press **Software activation**:





Alternatively, press main menu $\mathbf{Project} \to \mathbf{About} \ \mathbf{Software}$, and press $\mathbf{Software}$ $\mathbf{Activation}$.

- 2. Select one of the following methods to activate your SurPad:
 - o Manual code activation: internet is required.
 - o Online activation: internet is required.
 - o **Offline activation**: internet is not required.
 - Transfer activation code: internet is required. With this code, you can use SurPad on different devices.



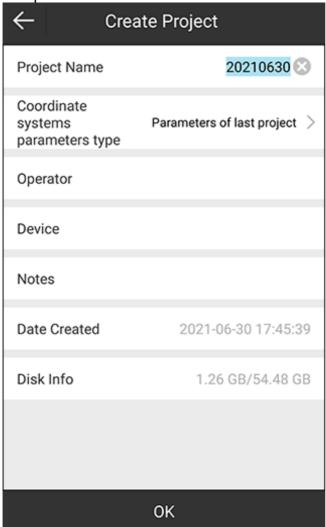
2.2 Create a New Project and Set Coordinate Parameters

In general, when you begin to measure an area at the first time, you need to create a project file matched with the current project coordinates.

After the project has been created, a file folder whose name is the same with the project will be created to save all data under directory *SurPad/Project* in your Android device.

To create a new project and set coordinate parameters, run SurPad, and do the following:

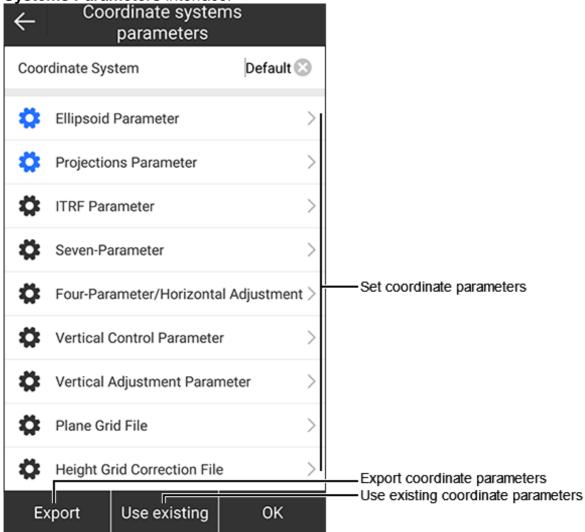
1. To enter **Create Project** interface, press main menu **Project** → **Project Manager**, and press **New**:



- 2. Set the following required parameters:
 - o **Project Name**: the created date by default.
 - Coordinate systems parameters type: including parameter of last project, local parameters, RTCM1021~1027 parameters, and CORS encrypted parameters.
- 3. **Optional:** Set the following additional parameters based on your need:
 - Operator
 - o Device
 - Notes
- 4. Press OK.



5. Optional: If Coordinate systems parameter type is set to Parameter of last project or Local parameters, set the coordinate system parameters in Coordinate Systems Parameters interface:



See 3.3 Coordinate System for details.

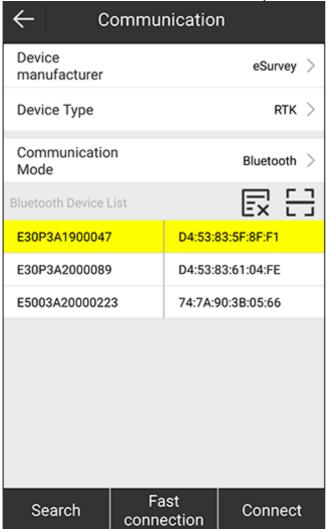


2.3 Connect to the Receiver

It is used to establish the communication between the receiver and the SurPad.

To connect to the receiver, do the following:

1. To enter **Communication** interface, press main menu **Device** → **Communication**:



- 2. Select the device manufacturer and the device type.
- 3. Select one of the following communication modes:
 - Bluetooth: to connect the receiver by Buletooth. Its operation is the same with WIFI operation.
 - WIFI: to connect the receiver by WIFI. Its operation is the same with Bluetooth operation.
 - Serial port: to connect the receiver with a data cable by setting port and baud.
 - Demo: to check and try out various functions of SurPad in demo mode by setting coordinates of the start point.



- 4. Taking the communication mode **Bluetooth** as an example, to set the communication mode, do the following:
 - a. To find receivers in **Bluetooth Device List**, press **Search**.
 - b. When the receiver you need to connect shows in the device list, press **Stop**.
 - c. Press the target Bluetooth, and press **Connect**.

CAUTION: Fast Connection is to search the signal around and automatically connect to the strongest one.

d. **Optional**: Press **Pair** in the pairing prompt if it is the first time to connect to the receiver.

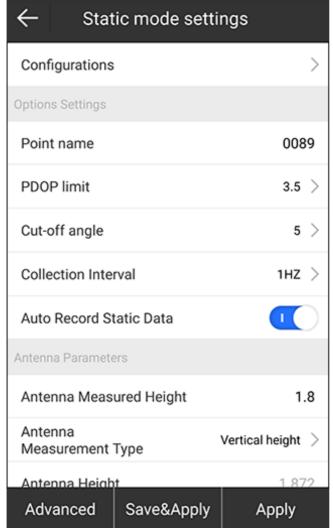
2.4 Set the Static Station

It is used to set the static, including configuration, option settings, antenna parameters, etc.

See 4.4 Static for details.

To set the base station, do the following:

1. To enter **Static Mode Settings** interface, press main menu **Device** → **Static**:



2. Press **Configurations** to select the configuration.



- 3. In **Options Setting** area, set point name, PDOP limit, cut-off angle, collection interval, and automatic static data recording.
- 4. In **Antenna Parameters** area, set antenna measured height, antenna measurement type and antenna height.
- 5. Press Apply.

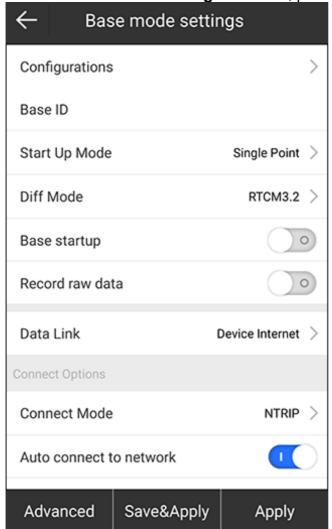
2.5 Set the Base Station

It is used to set the base, including configuration, base ID, start up mode, differential mode, base startup, raw data recording, data link, etc.

See 4.3 Base for details.

To set the base station, do the following:

1. To enter **Base Mode Settings** interface, press main menu **Device** → **Base**:



- 2. Press **Configurations** to select a saved configuration.
- 3. Set Base ID.
- 4. Press **Start Up Mode** to set a start up mode.
- 5. Select whether to enable base startup and record raw data.
- 6. Press **Datalink** to select a way to transmit differential signals.
- 7. Press Apply.



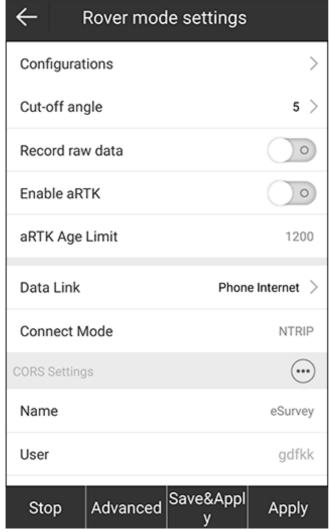
2.6 Set the Rover Station

It is used to set the rover, including configuration, cut-off angle, raw data recording, aRTK, aRTK age limit, data link, etc.

See 4.2 Rover for details.

To set the rover station, do the following:

1. To **Rover mode settings** interface, press main menu **Device** → **Rover**:



- 2. Press **Configurations** to select a saved configuration.
- 3. Set or select the cut-off angle.
- 4. Select whether to record raw data and enable aRTK.
 With raw data recorded, you can input point name and collect post-differential point.
- 5. Set the aRTK age limit.
- 6. Press **Data Link** to select a way to transmit differential signals.
- 7. Press Apply.

Return to the main interface to see if the status is fixed solution



in the status bar.

2.7 Do Surveying

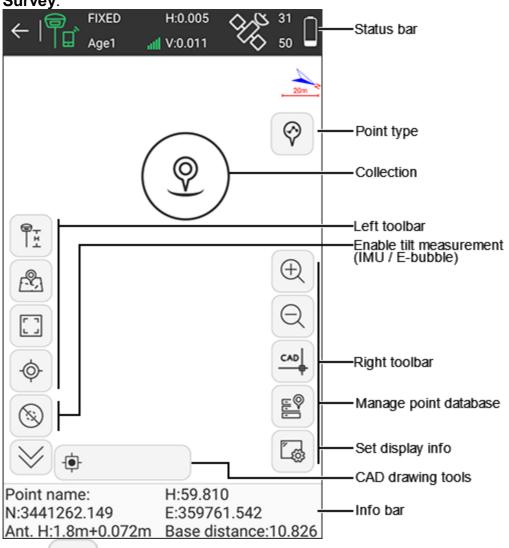
It is used to start your surveying work.



See <u>5.1</u> Point Survey for details.

To do surveying, do the following:

 To enter the main interface of point survey, press main menu Survey → Point Survey:



- 2. Press and select a point type.
- 3. **Optional:** Press and enable tilt measurement.
- 4. **Optional:** Press and manage point database.
- 5. **Optional:** Press , and set display information about the point type.
- 6. To collect the point, press



2.8 Export Data

It is used to export measurement data file into your needed data format for later use.

See 3.6 Export File for details.

To export data, do the following:

- 1. Copy the data file that needs to import to SurPad folder.
- 2. Press main menu **Project** → **Export File**.
- 3. Select the target data file, enable whether to export road cross-section, file format, and angle format.
- 4. Press **Export**.
- 5. Select the target file storage (internal storage root directory or program storage directory).
- 6. **Optional:** Modify the file name. The default one consists of the current data and time.
- 7. Press Export again.

A prompt Export file succeeded pops up.

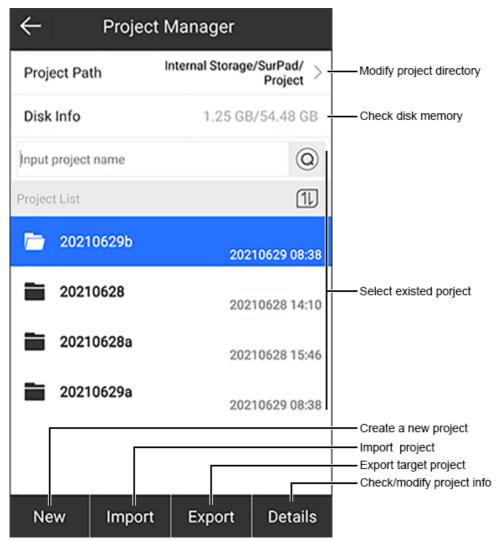


3 Project

SurPad manages data in the form of engineering documents, that is, all operations are controlled in a project. Every time you start SurPad, the software will automatically invoke engineering documents used last time.

3.1 Project Manager

Press main menu **Project** → **Project Manager** to enter **Project Manager** interface:



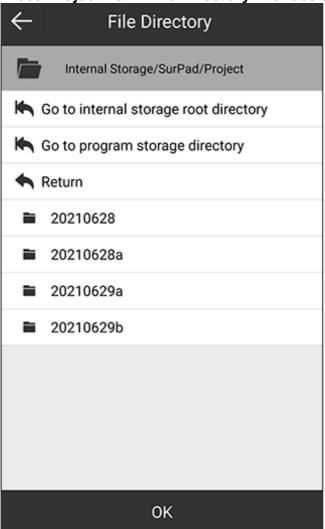


3.1.1 Modify the Project Directory

It is used to change the storage directory of the current project.

To modify the project directory, do the following:

1. Press Project Path. File Directory interface shows:



2. Select the target directory.

CAUTION: If the workload is large in survey, please make sure the memory of the target directory is sufficient to save the project.



3.1.2 Create a New Project

To create a new project, see <u>2.2</u> Create a New Project and Set Coordinate Parameters for details.

3.1.3 Select a Existed Project

It is used to select a project as the current project if you have created projects before.

To select an existed project, do one of the following:

- To find a project in the local by its project name, input the project name, and press
- To find a project in the local by the project list, in the Project List area, select a file folder.
 - If there are too many file folders, to quickly find the target one, you can press \blacksquare and select a sorting method.
- To import a project in other directories, press Import, select the target file directory and project.

3.1.4 Export a Project

To export a project, do the following:

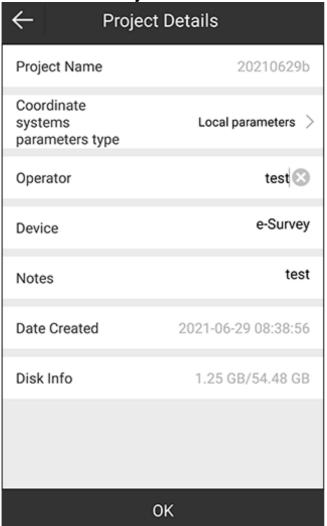
- 1. In the **Project List** area, select the target project.
- 2. Press **Export** and select the target file directory.



3.1.5 Check / Modify Project Information

To check / modify the project information, do the following:

1. Press Details. Project Details interface shows:



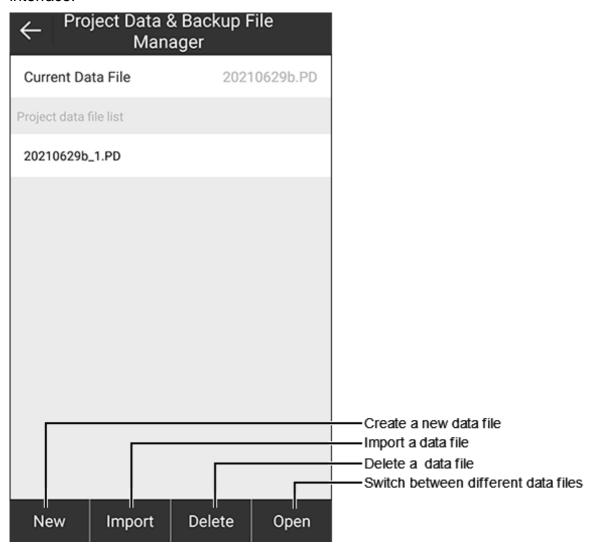
- 2. **Optional:** Modify the following information based on your needs:
 - o Coordinate systems parameters type
 - Operator
 - Device
 - Notes



3.2 Project Data Manager

It is used in a project where there is too much data or when you want to distinguish between two different coordinate point libraries.

Press main menu **Project** → **Project Data Manager** to enter **Project Data Manager** interface:



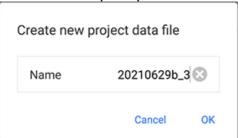
3.2.1 Create a New Data File

It is used to create a new data file with PD format to save the recorded survey data. The new data file is the data file for the storage record of the current project, and it belongs to the current project.



To create a new data file, do the following:

1. Press New. A prompt Create new project data file shows:



2. Set a name for the created data file.

Default: the current data file name_1/2/3... (accumulating)

3.2.2 Import a Data File

It is used to import a data file with RTK format.

To import a data file, do the following:

- 1. Select the target data file in **Project data file list** area.
- 2. Press Import. Import Backup File interface shows:



- 3. Press File Path and select the file path.
- 4. Set a name for the imported data file.



Default: the current data file name_1/2/3... (accumulating)

3.2.3 Delete a Data File

To delete a data file, do the following:

- 1. In **Project data file list** area, select the target file.
- 2. Press **Delete**. A prompt for confirmation shows.
- 3. Press OK.

3.2.4 Switch between Different Data Files

It is used to switch between different data files when a project owns multiple data files.

To switch between different data files, do the following:

- 1. In **Project data file list** area, select the target file.
- 2. Press Open.

3.3 Coordinate System

It is used to set coordinate system parameters.

Press main menu $Project \rightarrow Coordinate System$ to enter Coordinate Systems Parameters interface.

The interface differs in the coordinate system parameter type when a project is created:

- Local parameters
- RTCM1021~1027 parameters: a way to send coordinate system parameter via differential data. In this way, the software analyses coordinate parameters from received differential data.

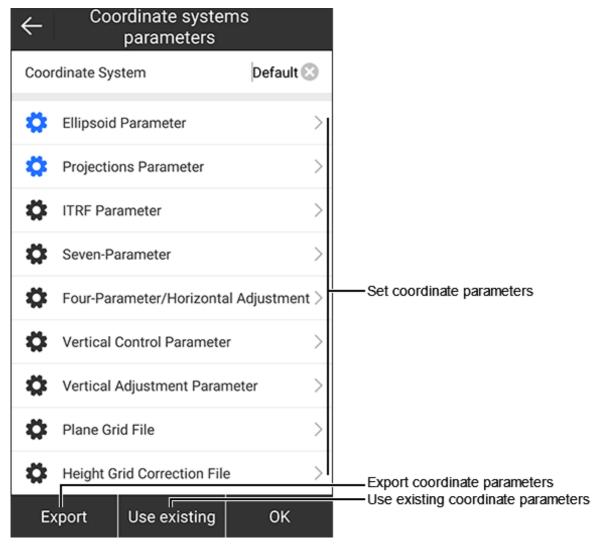
The **Coordinate Systems Parameters** interface is unchangeable.

CORS encrypted parameters: it is mainly used by CORS merchants when they
would like to keep coordinate parameters secret.

The **Coordinate Systems Parameters** interface is unchangeable.



Taking parameter type **local parameters** as an example, the interface is as follows:



3.3.1 Set Coordinate Parameters

To set coordinate parameters, do the following:

- 1. Set a name for the coordinate system.
- 2. Set the following parameters according to the actual situation:
 - Ellipsoid parameter: to select the target ellipsoid or customize the ellipsoid. With the customized ellipsoid, please set the semimajor axis and reciprocal of flattening 1/f, which should be the same with the ellipsoid used for parameter calculation.
 - Projection parameter: it contains most of the frequently-used projection modes, such as UTM, Gauss Kruger, Transverse Mercator, Lambert Conic Conformal, etc.
 - During setting projection parameters, when the central meridian is not the
 - same with the actual situation, you can press or manually input the current central meridian.
 - o **ITRF parameter**: ITRF refers to International Terrestrial Reference Frame.
 - Seven parameter: to perform Space rectangular coordinate transformation within two different ellipsoids.



- Four-parameter/horizontal adjustment: in general at least two known points and four pairs of XY coordinate values in two different space rectangular coordinate systems are required to calculate the four unknown parameters.
- Vertical control parameter: to use some known points to calculate the vertical control parameters, in order to match the elevation of receivers with the local height system.
- Vertical adjustment parameter: the elevation transformation model of Trimble TGO software.
- Grid file: to match the horizontal difference (North and East) between the local and universal coordinate system, and import the grid file (*.GDS, *.GSB, *.GFS).
- Geoid file: to match the earth height (ellipsoid height used in GPS elevation system) with the normal height (used in elevation system in survey), and import the geoid file (*.GGF, *.SGF, *.UGF, *.GSF).
- o Local offsets: to calculate local offsets based on a known point.

3.3.2 Use Existing Coordinate Parameters

It is used to apply coordinate system parameters stored before.

To use existing coordinate parameters, do the following:

- 1. Press Use existing.
- 2. Select one of the following methods to apply coordinate parameters:
 - o **Local disk**: to apply them in the local. SP and EP formats are supported.
 - o **QR code**: to apply them by scanning the QR code.
 - Cloud server: to apply them from the cloud server.
 See 3.8 Cloud Settings for details.
 - o **Predefined projections**: to apply predefined parameters saved before.

3.3.3 Export Coordinate Parameters

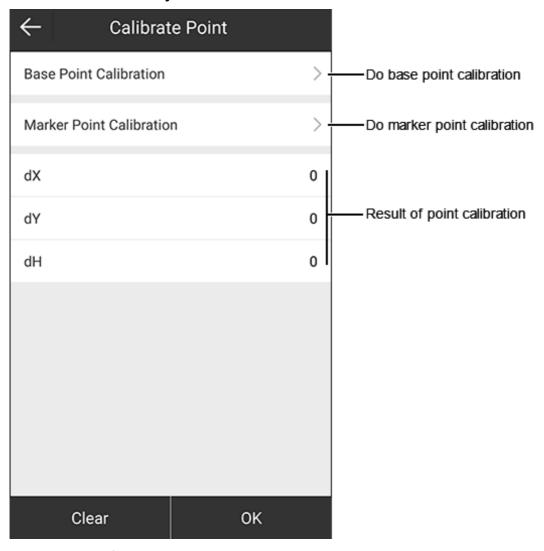
To export coordinate parameters, do the following:

- 1. Press Export.
- 2. Select one of the following methods to export the set coordinate parameters:
 - Local Disk: to save them in the SurPad files in the local.
 - o **QR Code**: to save them as a QR code.
 - o Cloud Server: to upload them to the cloud server.



3.4 Calibrate a Point

Press main menu **Project** → **Calibrate Point** to enter **Calibrate Point** interface:



There are the following ways to calibrate a point:

 Base point calibration: the base station is set up at known control points and has been leveled and centered.



CAUTION: This function is rarely used in the measurement.

 Marker point calibration: the base station is not set up at a known control point when it has been turned on / off or its position has been changed, and the rover station is set up at known control points.

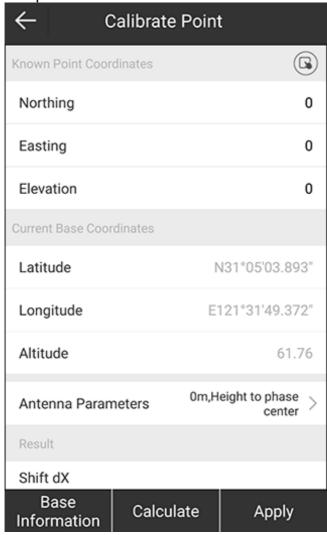


3.4.1 Do Base Point Calibration

By inputting coordinates of a known point and WGS84 coordinate automatically obtained when the base station is started, SurPad will calculate calibration parameters of the base station.

To do base point calibration, do the following:

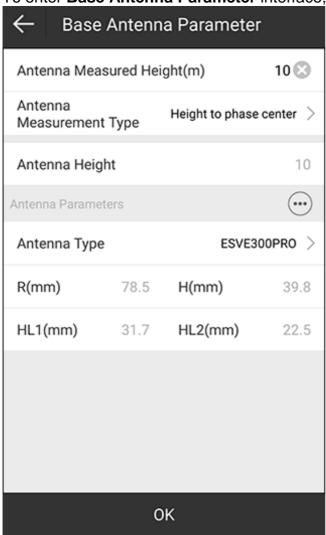
1. To enter Calibrate Point interface, press main menu Project → Calibrate Point, and press Base Point Calibration:



- 2. To input a known point, do one of the following:
 - To select a point from the point database, press and select the target point.
 - To manually input coordinates, set values of Northing, Easting and Elevation.



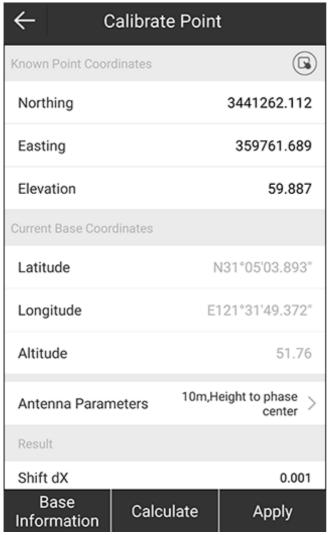
3. To enter Base Antenna Parameter interface, press Antenna Parameters:



- 4. Set the following antenna parameters, and press **OK** to return to **Calibrate Point** interface:
 - Antenna Measured Height
 - Antenna Measured Type: including pole height, height to phase center, slant height, slant height to altimetry.
 - Antenna Type: it is automatically set according to the current connected receiver.



5. To check the calculation result, press **Calculate**. The result is shown in **Result** area:



If the calculation result is in red font in **Result** area, it indicates the translation parameter is out of range (the longitude difference or latitude difference over 1°, or the height difference over 1000°).

6. To directly apply the calculation result, press **Apply**.

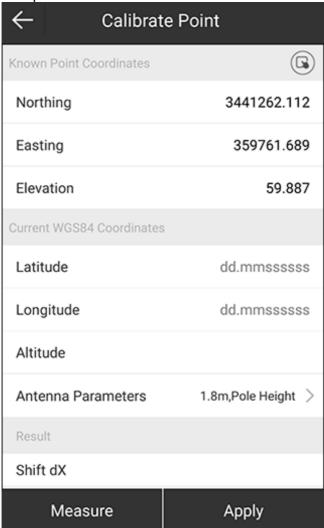


3.4.2 Do Marker Point Calibration

By inputting coordinates of a known point and the generated WGS84 coordinate, SurPad will calculate calibration parameters of the rover station.

To do marker point calibration, do the following:

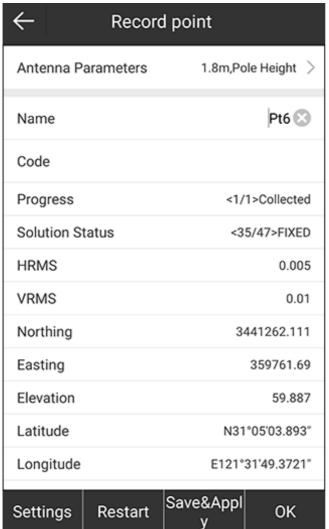
1. To enter Calibrate Point interface, press main menu Project → Calibrate Point, and press Marker Point Calibration:



- 2. To input a known point, do one of the following:
 - To select a point from the point database, press and select the target point.
 - To manually input coordinates, set values of Northing, Easting and Elevation.



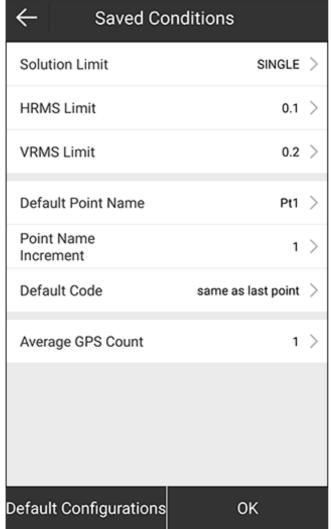
3. Press Measure. Record Point interface shows:



4. Set a name and code.



5. To set saved conditions, press **Setting**, and set related parameters in **Saved Conditions** interface, and press **OK** to return to **Record point** interface:



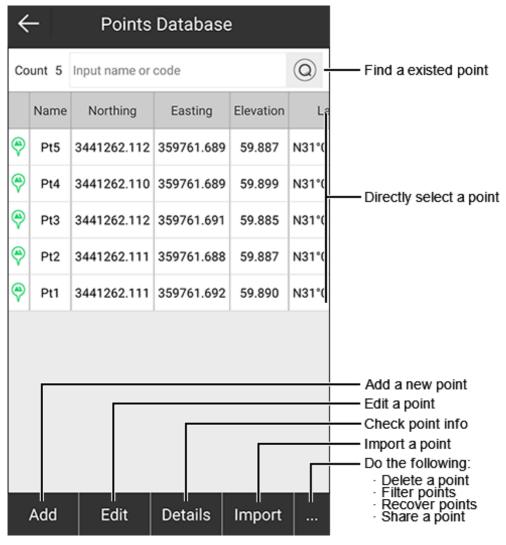
- 6. Press Antenna Parameters, and set antenna parameters.
- 7. Press **OK** to return to **Calibrate Point** interface. The result shows in **Result** area.
- 8. To directly apply the calculation result, press **Apply**.



3.5 Point Database

It is used to manage all types of coordinate points.

Press main menu **Project** → **Points Database** to enter **Points Database** interface:



3.5.1 Find the Existed Point

To find the existed point, do the following:

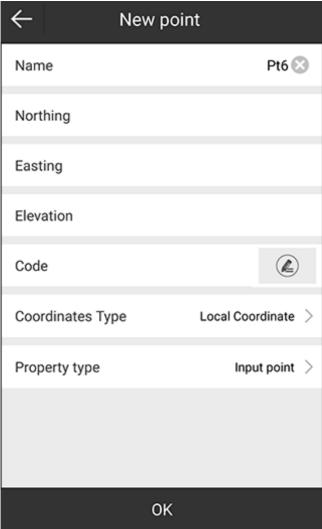
- 1. Input a name or a code of the existed point in input box of **Count n**.
- 2. Press Q



3.5.2 Add a New Point

To add a new point, do the following:

1. Press Add. New Point interface shows:



- 2. Input a name.
- 3. Select a coordinate type:
 - Local Coordinate
 - o Geodetic Coordinate
- 4. Set one of the following coordinates:
 - o If the coordinate type is set to **Local Coordinate**, set northing, easting and elevation.
 - If the coordinate type is set to Geodetic Coordinate, set latitude, longitude and altitude.



- 5. To set a code, do one of the following:
 - o Directly input a code name.





← Code Library Manager					
No.	Name		Full Pa	th	
1	a1	Internal Storage/SurPad/Config/a1.txt			
2	a2	Internal Storage/SurPad/Config/a2.txt			
3	a3	Internal Storage/SurPad/Config/a3.txt			
N	ew	Edit	Delete	Import	ок

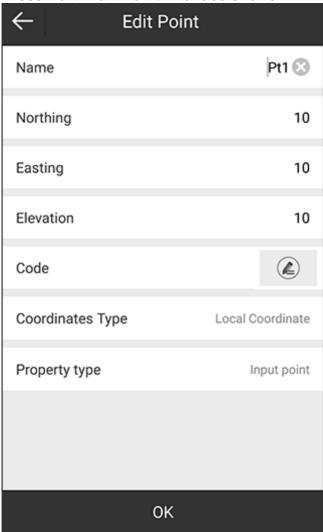
- 6. Select a property type:
 - Assistant point
 - Control point
 - Input point
 - Stakeout point



3.5.3 Edit a Point

To edit a point, do the following:

- 1. Select a point.
- 2. Press Edit. Edit Point interface shows:



- 3. Modify the following based on your needs:
 - Name
 - o **Coordinate**: including northing, easting and elevation. It is only for input points. For measured points, this is unavailable.
 - o Code



3.5.4 Check Point Information

It is used to check the point name, code, latitude, longitude, altitude, northing, easting, elevation, coordinates of X, Y and Z, and property type.

To check point information, do the following:

- 1. Select a point.
- 2. Press **Details**. **Point Details** interface shows:

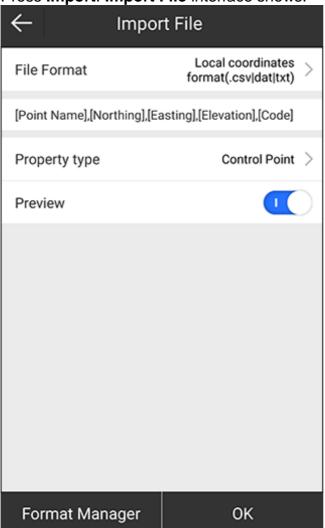
	Point Details		
Title	Content		
Point Name	Pt4		
Code			
Latitude	N31°05'03.893"		
Longitude	E121°31'49.372"		
Altitude	59.899		
Northing	3441262.11		
Easting	359761.689		
Elevation	59.899		
×	-2859084.051		
Υ	4660052.802		
z	3273943.182		
Photo And Sketch			



3.5.5 Import a Point

To import a point, do the following:

1. Press **Import**. **Import File** interface shows:



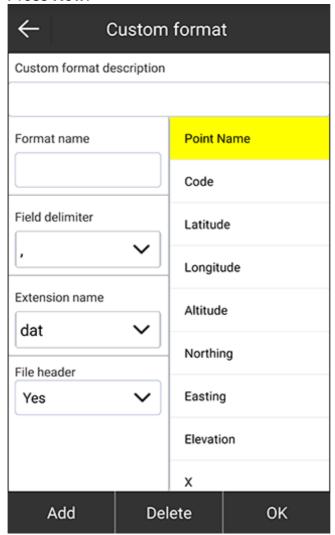


- 2. **Optional:** To add a user-defined format, do the following:
 - a. Press Format Manager:

← User-defined format					
No.	Format name	Extension name			
1	test	dat			
2	test1	dat			
3	test2	txt			
4	test3	csv			
5	test4	xIs			
New		Edit Imp	ort Delete		



b. Press **New**:



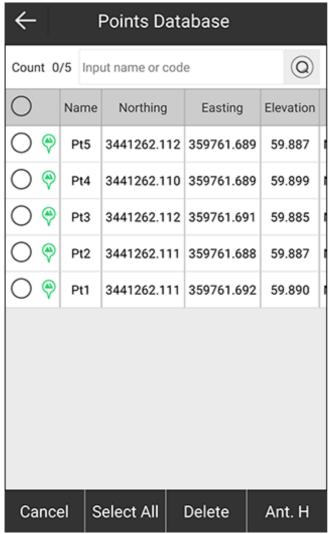
- c. Set format name, field delimiter, extension name and add format description.
- d. Press **OK**. The add user-definded format shows in the existed file formats.
- 3. Press File Format, and select one of the following existed file formats:
 - o Measurement data file (.PD): preview is not supported.
 - Geodetic coordinates format (.csv / .dat / .txt)
 - Local coordinates format (.csv / .dat / .txt)
 - COT format (.cot)
 - Cass format (.dat)
 - AutoCAD format (.dxf)
 - GoogleEarth kmz file format (.kmz)
 - NETCAD format (.ncn)
 - o PXY file (.pxy)
 - Carlson coorinate file (.crd)
 - Spatial coordinate (.csv / .dat / .txt)
 - User-defined formats
- 4. Select a property type.
- 5. **Optional:** To preview the point, enable **Preview**.
- 6. Press OK.
- 7. Select the target file directory and the target file.
- 8. Preview the data, and press **OK** to import coordinates if the data is correct.



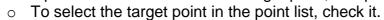
3.5.6 Delete a Point

To delete a point, one of the following:

- 1. Do one of the following:
 - Long press the target point in Points Database.
 - \circ Press ... \rightarrow Delete.



- 2. To select the target point, do one of the following:
 - Input the name or code of the target point, and press .

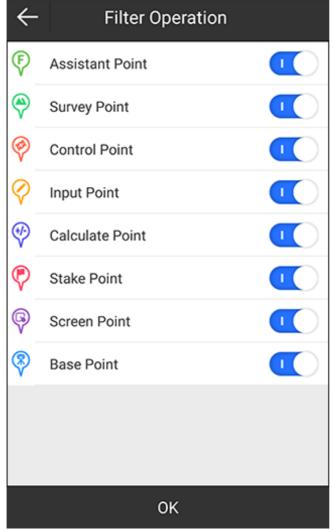




3.5.7 Filter Points

To filter points, do the following:

1. Press $\dots \rightarrow$ Options. The Filter Operation interface shows:



2. Enable or disable the target point type.

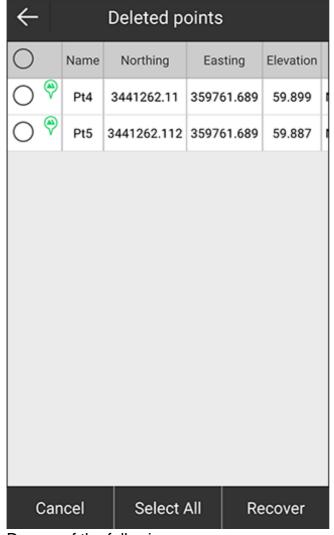


3.5.8 Recover Points

It is used to recover points you deleted.

To recover points, do the following:

1. Press $\dots \to \text{Recover}$. The **Deleted Points** interface shows:



- 2. Do one of the following:
 - Check the target point(s).
 - o To select all points, press **Select All**.
- 3. Press Recover.

The target point(s) show(s) in **Point Database** interface again.



3.5.9 Share a Point

To share a point, do the following:

- 1. Select the target point in **Points Database** interface.
- 2. Press $\dots \rightarrow$ **Share**. A QR code of the target point is automatically generated:



3. Press QR Code, and select the target app on your device.

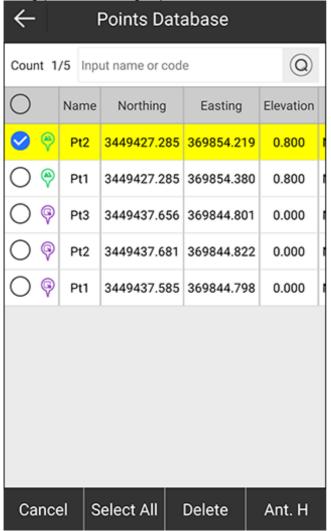


3.5.10 Modify Antenna Parameters

It is used to modify antenna parameters of points except screen points, so as to adjust the coordinates of points.

To modify antenna parameters, do the following:

1. Long press the target point in **Points Database** interface:



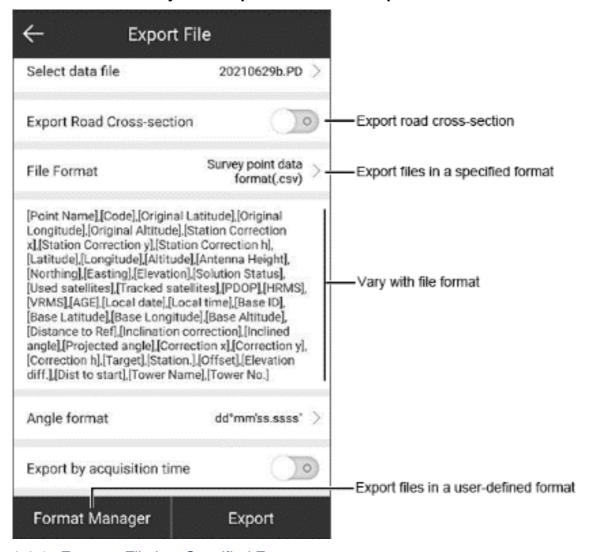
- 2. Optional: Check all target points.
- 3. Press Ant.H. Antenna Parameters interface shows.
- 4. Set antenna measure height and antenna measurement type.



3.6 Export File

It is used to export measurement data file into the data format that you need.

Press main menu **Project** → **Export File** to enter **Export File** interface:



3.6.1 Export a File in a Specified Format

To export files in a specified format, do the following:

- 1. Select a data file.
- 2. Select one of the following file formats:
 - Survey point data format (.csv)
 - Survey point data format (.xls)
 - TPS Survey point data format (.csv)
 - Cass format (.dat)
 - KS Scsq2000 (.dat)
 - Local coordinates format (.dat)
 - Geodetic coordinates format (.dat)
 - Name, North, East, Elevation, Station, Offset (.dat)
 - AutoCAD format (.dxf)
 - GoogleEarth kml file format (.kml)
 - GoogleEarth kmz file format (.kmz)

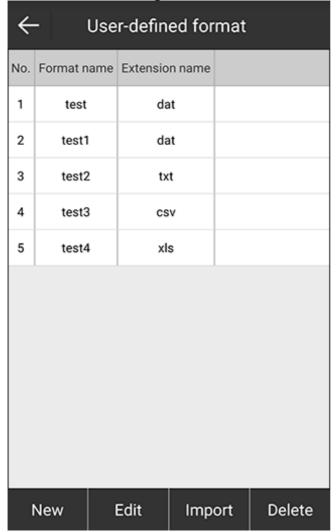


- SW electric file format (.swd)
- Track file format (.gpx)
- DOL file format (.csv)
- DOL file format (.html)
- LSS file format (.001)
- Photo and Skethc (.jpg)
- NETCAD format (.ncn)
- o PXY file (.pxy)
- Carlson coordinate file (.crd)
- Cadastral surveying data format (.PD)
- GNSS Survey Report (.xls)
- 3. Press Export.

3.6.2 Export a File in a User-defined Format

To export a file in a user-defined format, do the following:

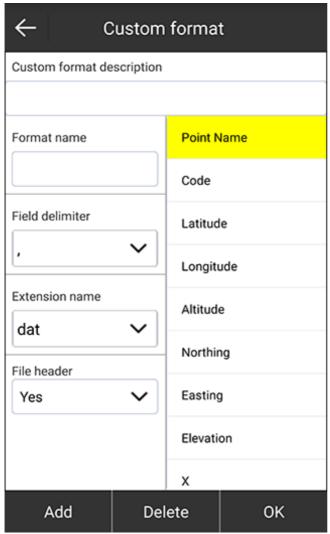
1. Press Format Manager. User-defined format interface shows:



- New: to create a new customized file format.
- o **Edit**: to edit the created file format.
- o **Import**: to import a customized file format.
- Delete: to delete the created customized file format.



2. Press New. Custom format interface shows:



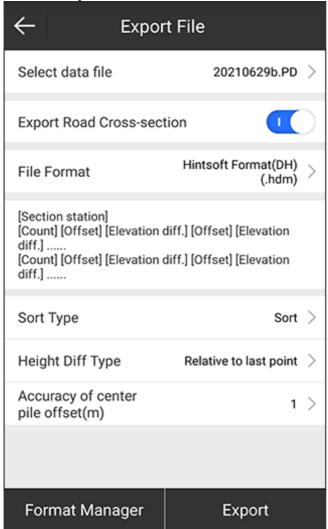
- 3. Set the following:
 - Format name
 - o Field delimiter: , @ Space Tab Enter
 - o Extension name: dat, csv, txt, xls
 - o File header
- 4. Select the exported format content, and press **Add** to add the content to the input box of **Custom format description**.
- 5. **Optional:** To delete the content of the custom format description one by one, press **Delete**.
- 6. Press **OK**. The interface returns to **User-defined format**.
- 7. Go back to **Export File** interface, and select a data file.
- 8. Select the customized file format.
- 9. Press Export.



3.6.3 Export Road Cross-section

To export road cross-section, do the following:

1. Enable Export Road Cross-section. The following interface shows:



The interface varies with the file format.

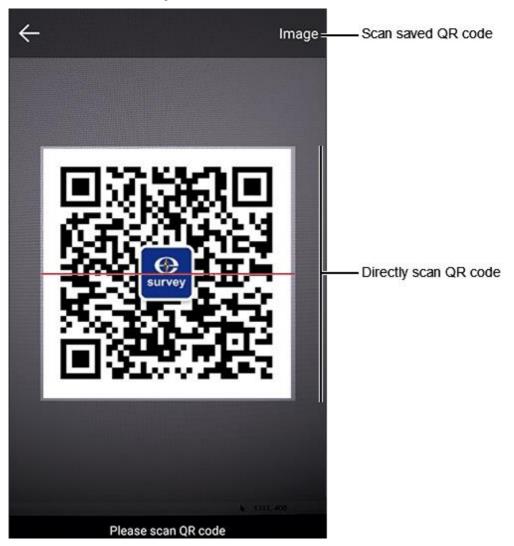
- 2. Select a data file.
- 3. Select a file format:
 - Hintsoft format (DH)(.hdm)
 - TianZhen format (H) (.hdm)
 - SOUTH CASS Cross-section file format (.hdm)
 - o Haiti (.hdm)
 - Section measurement data (.csv)
- 4. Do related settings.
- 5. Press Export.



3.7 Scan QR Code

It is mainly used to scan the QR code of coordinate system and configuration set.

Press main menu **Project** → **Scan QR Code** to enter **Scan QR Code** interface:



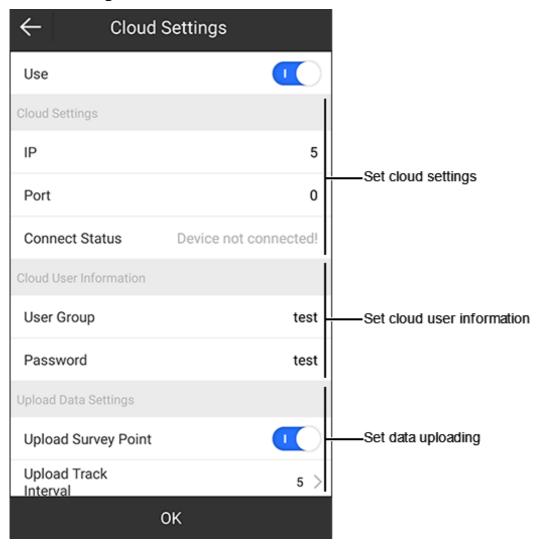
After scanning the QR code, you can view detail information and apply the data in the current project.



3.8 Cloud Settings

It is a customized function. Please contact us if necessary.

Press main menu **Project** → **Cloud Settings**, and turn **Use** switch to **ON** status to enter **Cloud Settings** interface:



You can use existing coordinate parameters through cloud server by pressing main menu $Project \rightarrow Coordinate System$.



3.9 Software Settings

It is used to set the following:

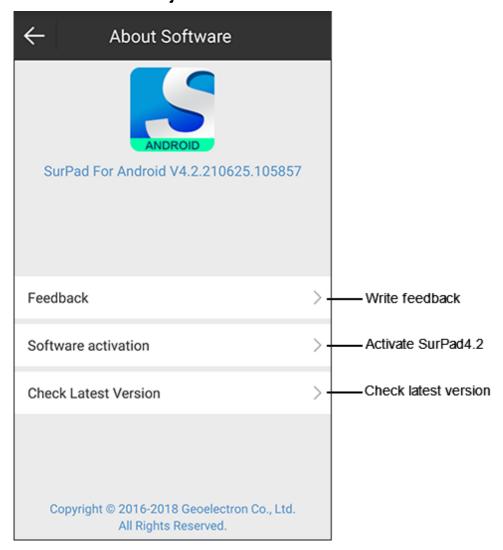
- General settings: including shortcuts, software update notification, and voice prompt.
- Record settings: including topo point, control point, quick point, auto point, corner point, stop & go point, and tilt point.
- System settings: including distance unit, distance decimal, angle format, angle decimal, station format, language, text encoding, survey point data backup, change alert of base coordinates, location services, and auto start at boot.
- Display settings: including CAD background color, display content, coordinate order habit, display type, last (0 ~ 100) points, screen orientation, full screen display, and map display.

To do software settings, press main menu **Project** → **Software Settings** to enter **Software Settings** interface, and modify related settings based on your needs.

3.10 About Software

It is used to check feedback, activate the software and check the latest version.

Press main menu **Project** → **About Software** to enter **About Software** interface:

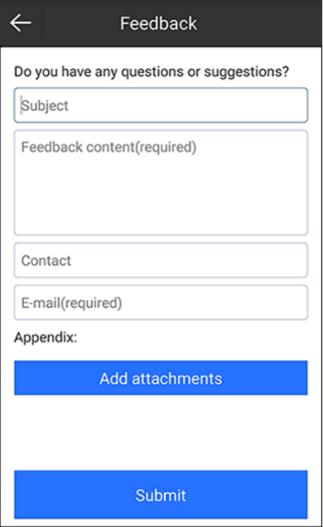




3.10.1 Write Feedback

To write feedback, do the following:

1. Press Feedback. Feedback interface shows:



- 2. Write your feedback.
 Attachments are available.
- 3. Press Submit.

3.10.2 Activate the SurPad

See 2.1.2 Activate the SurPad for details.

3.10.3 Check the Latest Version

It is used to check if the current software is the latest version.

To check the latest version, press **Check Latest Version**:

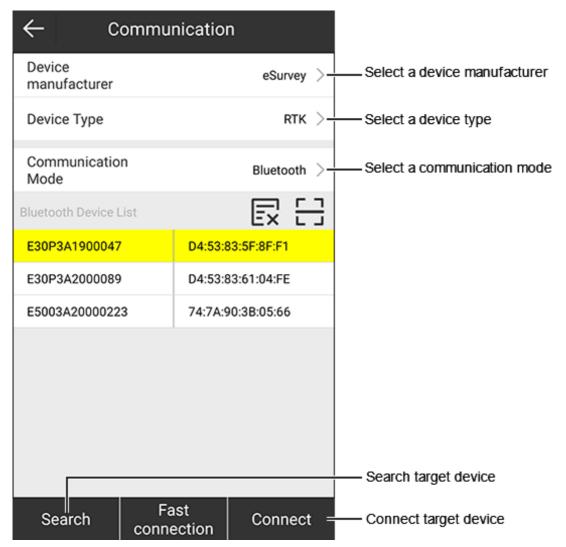
- If it is the latest version, the interface shows **Latest version**.
- If not, a prompt *New version found. Update now?* shows to remind you to update the software.



4 Device

4.1 Communication

Press main menu **Device** → **Communication** to enter **Communication** interface:



The device type differs in the device manufacturer. Connection to a total station is supported.

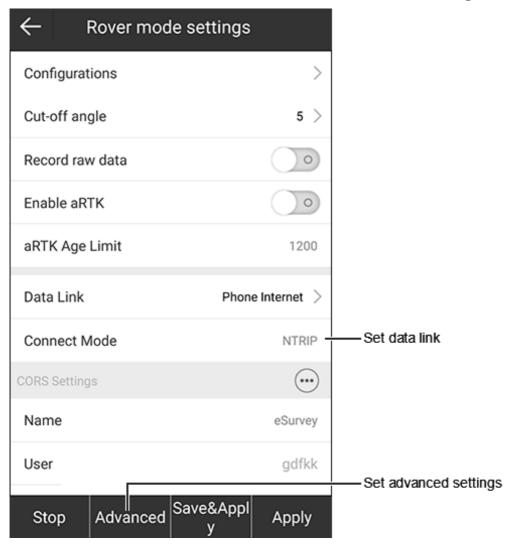
See 2.3 Connect to the Receiver for details.



4.2 Rover

It is used to set the receiver as the rover station.

Press main menu **Device** → **Rover** to enter **Rover mode settings** interface:



- **Cut-off angle**: the minimum vertical angle that is allowed to receive satellite signals. Signals below the angle will be ignored.
- **Record raw data**: to select whether to record raw data.

 With raw data recorded, you can set point name and collect post-differential point.
- **Enable aRTK**: to select whether to enable aRTK. With it enabled, the receiver is able to generate RTK positions even if the RTK correction source becomes unavailable within the set aRTK age limit.
- **Data link**: to select a way to transmit differential signals:
 - o **None**: no differential signals is transmitted.
 - o **Device Internet**: through the internal network in the receiver via a SIM card.
 - o **External Radio**: through an external radio connected with the receiver.
 - o **Phone Internet**: through the network of the used device.
 - o **Internal Radio**: through the internal radio.

4.2.1 Set the Data Link

It is used to set the current data link.



To set the data link, do one of the following:

- If the data link is set to **Device Internet**, set the following:
 - In Connect Mode area, set the following:
 - Connect mode
 - NTRIP: the standard network transmission differential mode, commonly used in CORS networks.
 - CSD: the original form of data transmission developed for the time-division multiple access (TDMA)-based mobile phone systems.
 - **TCP client**: one of the main protocols of the Internet protocol suite. It can be used to transfer differential data.
 - **Custom**: the user defined mode.
 - GGA upload interval (s): default value: 5.
 - Auto connect to network: to select whether the receiver automatically connects to the internet once it is powered on.
 - Network mode: including GPRS and WIFI (the receiver should equip with WIFI function).
 - Network system: including auto, GSM, and CDMA1x.
 - **Network relay**: to select whether to use network relay.
 - o In **APN Settings** area, select whether to automatically connect to APN, or set operator, name, user and password.

In addition, you can press eafter **APN Settings** to add an APN.

- o In CORS Settings area, set name, user and password.
 - In addition, you can press after **CORS Settings** to customize information about the CORS server.
- In MountPoint Settings area, set mount point, select whether to enable phone internet access, and press Get Mount Point.
- If the data link is set to External Radio, set baud rate.

Default baud rate: 38400

- If the data link is set to Phone Internet, set the following:
 - In CORS Settings area, set name, user and password.

In addition, you can press after CORS Settings to customize information about the CORS server.

- In MountPoint Settings area, set mount point, and press Get Access Point.
- o In **Receive Data** area, select whether the receiver automatically connects to the internet once it is powered on.
- If the data link is set to Internal Radio, set the following:
 - Channel and frequency: channel 1~7 is fixed whose frequency is unchangeable; channel 8 is user-defined whose frequency can be set as needed.

CAUTION: With this data link, the frequency and protocol settings of the rover and base should be the same.

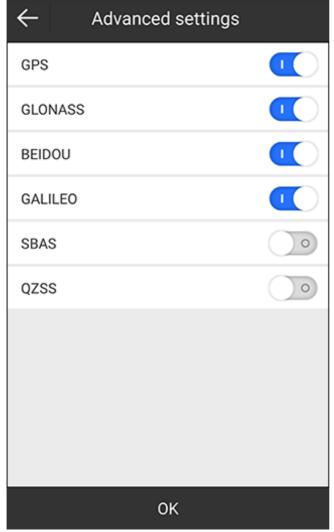


 Protocol: including Satel, PCC-4FSK, PCC-GMSK, TrimTalk 450S, HiTarget(9600), HiTarget(19200), South 9600, Trimmari III, South 19200, TrimTalk(4800), PCC-GMSK(4800), GEOTALK, GEOMARK, etc.

4.2.2 Set Advanced Settings

To set advanced settings, do the following:

1. Press Advanced. Advanced Settings interface shows:



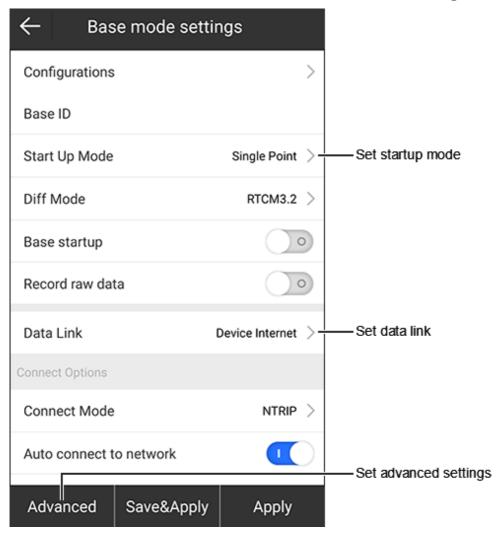
- 2. Select whether to receive signals from the following systems:
 - o GPS
 - GLONASS
 - o **BEIDOU**
 - o GALILEO
 - SBAS: the wide-area differential augmentation system (satellite-based augmentation system).
 - o QZSS



4.3 Base

It is used to set the receiver as the base station.

Press main menu **Device** → **Base** to enter **Base mode settings** interface:



CAUTION: If the receiver is not in the base mode, you can directly modify its base parameters and set the receiver as the base station; if it is, you need to stop the base station before modifying its base parameters.

- Base ID: ID of the base station.
- Startup mode: including single point and input base coordinates.
- **Diff mode**: including RTCM3, CMR, CMR+, DGPS and RTCM32.
- Base startup: to select whether the base station automatically sends data after it is restarted.
- Record raw data: to select whether to record raw data.
 With raw data recorded, you can set point name and collect post-differential point.
- Data link: to select a way to transmit differential signals:
 - o **Device internet**: through the internal network via a SIM card or WIFI.
 - o **External radio**: through an external radio connected with the receiver.
 - o Internal radio: through the internal radio.
 - o **Dual**: through the device internet and external radio.



4.3.1 Set the Startup Mode

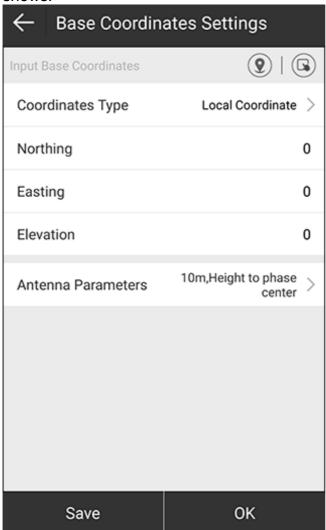
The supported startup modes include the following:

- **Single point**: to directly use WGS-84 coordinates of the current point as the base coordinates.
 - In this mode, point calibration for the rover station is required. See $\underline{3.4}$ Calibrate a Point for details.
- Input base coordinates: to manually input the base coordinates.

CAUTION: If the current position differs significantly from the input coordinates, please check the coordinate system or use single point mode to start base.

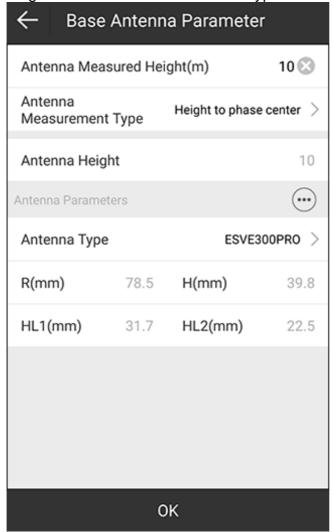
To set the startup mode by inputting base coordinates, do the following:

1. Select **Start up mode** as **Input base coordinates**. **Base Coordinates Settings** shows:





- 2. To get the base coordinates, do one of the following:
 - o To use the current GPS coordinates, press
 - To select a point from the point database, press and select the target point.
 - To manually input coordinates, select a coordinate type (geodetic coordinate or local coordinate), and set values of base coordinate.
- 3. To get antenna height, press **Antenna Parameters**, and set antenna measured height and antenna measurement type in **Base Antenna Parameter** interface:



The antenna type will be automatically recognized.

- 4. **Optional:** To save coordinates to the point database, press **Save** in **Base Coordinates Settings** interface.
- 5. To apply the base coordinate settings, press **OK**.



4.3.2 Set the Data Link

It is used to set the current data link.

To set the data link, do one of the following:

- If the data link is set to Device internet, set the following:
 - o In Connect options area, set the following:
 - Connect mode
 - NTRIP: the standard network transmission differential mode, commonly used in CORS networks.
 - **Custom**: the user defined mode.
 - ZHD: the differential transmission mode of HI-TARGET network, which needs to set group number and subgroup number.
 - **CHC**: the differential transmission mode of CHC network.
 - Auto connect to network: to set whether the receiver automatically connects to the internet once it is powered on.
 - Network mode: including GPRS and WIFI (the receiver should equip with WIFI function).
 - Network system: including auto, GSM, and CDMA1x.
 - In APN Settings area, select whether to automatically connect to APN, or set operator, name, user and password.
 - In addition, you can press eafter **APN Settings** to add an APN.
 - In CORS settings area, set NTRIP/CORS IP, port, base access point and server password.

For base access point, it is generally set to the device serial number.

In addition, you can press after **CORS Settings** to customize information about the CORS server.

- If the data link is set to External radio, set baud rate.
 Default baud rate: 38400.
- If the data link is set to **Internal radio**, set the following:
 - Channel and frequency: channel 1~7 is fixed whose frequency is unchangeable; channel 8 is user-defined whose frequency can be set as needed.

CAUTION: With this data link, the frequency and protocol settings of the rover and base should be the same.

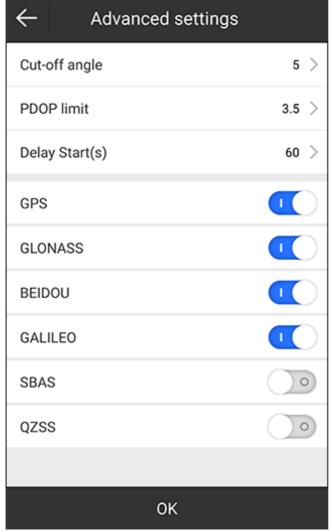
- Protocol: including Satel, PCC-GMSK, TrimTalk 450S, South 9600, HiTarget(9600), HiTarget(19200), TrimTalk(4800), GEOTALK, GEOMARK, HZSZ, etc.
- Power: the power level of the base will affect the operating distance of the radio:
 - Low power and low power consumption lead to short operating distance.
 - High power and high power consumption lead to long operating distance.
- If the data link is set to Dual, see settings when the data link is set to Device internet and External radio.



4.3.3 Set Advanced Settings

To set advanced settings, do the following:

1. Press Advanced. Advanced Settings interface shows:



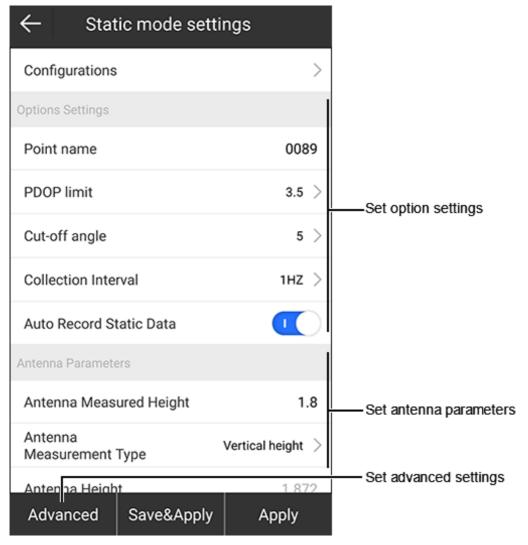
- 2. Set the following parameters:
 - Cut-off angle: the minimum vertical angle that is allowed to receive satellite signals. Signals below the angle will be ignored.
 - o **PDOP limit**: the geometric strength factor of the satellite distribution. The smaller the PDOP value is, the better the satellite distribution is. When it is less than 3, it is the ideal state.
 - Delay start (s): it will give time to get better signal tracking and provide stable correction data especially when the base station is just powered on and the signal tracking is not good.
- 3. Set whether to receive signals from related systems: See <u>4.2.2</u> Set Advanced Settings for details.



4.4 Static

It is used to set the receiver as the static station.

Press main menu **Device** → **Static** to enter **Static mode settings** interface:



4.4.1 Set Option Settings

To set option settings, in **Options Settings** area, set the following:

- **Point name**: the point name of static data. It should be within 4 characters.
- **PDOP limit**: the geometric strength factor of the satellite distribution. The smaller the PDOP value is, the better the satellite distribution is. When it is less than 3, it is the ideal state.
- **Cut-off angle**: the minimum vertical angle that is allowed to receive satellite signals. Signals below the angle will be ignored.
- **Collection interval**: nHZ represents that the acquisition of data group(s) per second; ns represents that the acquisition of a group of data within second(s). The maximum interval depends on the receiver GNSS activation status.
- **Auto record static data**: to select whether the receiver automatically starts recording when it is powered on.



4.4.2 Set Antenna Parameters

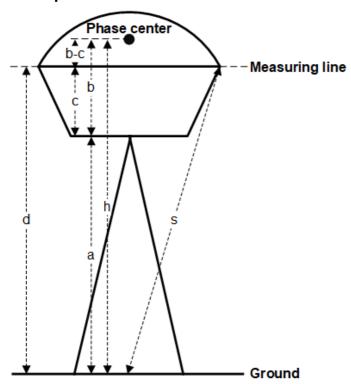
Since the antenna height cannot be directly measured, it is automatically calculated by SurPad based on the measured height you input and measurement type you select.

CAUTION: No matter what the value of measured height you input and what kind of measurement type you select, the value of antenna height is unique.

To set antenna parameters, in **Antenna Parameters** area, set the following:

- Antenna measured height: its meaning depends on the antenna measurement type.
- Antenna measurement type
 - Height from phase center
 - Slant height form measuring line
 - Vertical height from measuring line
 - Slant height form altimetry
 - Vertical height
- Antenna height: the vertical height from the phase center of the antenna to the ground.

Principle



Among them:

- **a**: the vertical height form the bottom of the receiver to the ground.
- **b**: the vertical height from the bottom of the receiver to the phase center.
- **c**: the vertical height from the bottom of the receiver to the measuring line.
- **b-c**: the vertical height from the phrase center to the measuring line.
- **d**: the vertical height from the measuring line to the ground.
- h: the antenna height.



- **s**: the slant height form the measuring line to the ground.
- R: the radius of the rubber ring.
- **S**: the slant height from the altimetry piece to the ground with the known radius (Rc) of the alitimetry piece.

There are the following ways to calculate the antenna height:

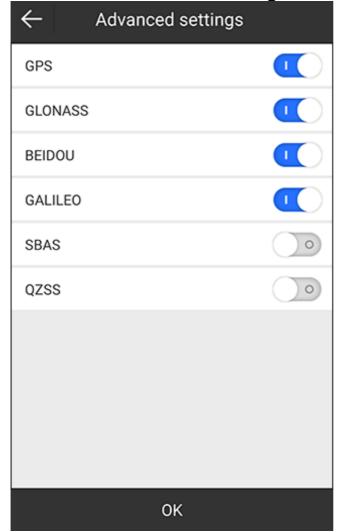
Measured height	antenna measurement type	Antenna height
h	Height from phase center	h = h
s	Slant height form measuring line	$h = sqrt (s^2 - R^2) + (b - c)$
d	Vertical height from measuring line	h = a + c + (b - c) = a + b
S	Slant height from altimetry	$h = sqrt (S^2 - Rc^2) + b$
а	Vertical height	h = a + b

4.4.3 Set Advanced Settings

It is used to set whether to receive signals from the corresponding systems.

To set advanced settings, do the following:

1. Press Advanced. Advanced Settings interface shows:



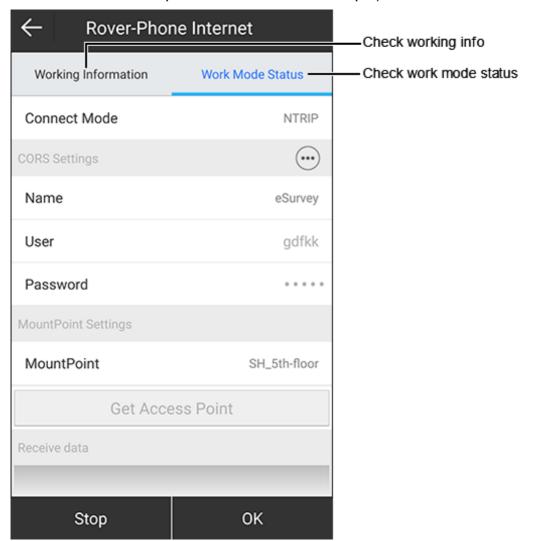


- 2. Set whether to receive signals from the following systems:
 - o GPS
 - GLONASS
 - o BEIDOU
 - o GALILEO
 - SBAS: wide-area differential augmentation system (satellite-based augmentation system).
 - o QZSS

4.5 Work Mode Status

It is used to check working information and work mode status.

Press **Device** → **Work Mode Status** to enter the following interface (taking rover station and data link is set to phone internet as an example):



- Working information: including cut-off angle, whether record raw data is enabled, whether aRTK is enabled, and whether GPS, BEIDOU, GLONASS, GALILEO, SBAS, or QZSS is enabled.
- Working mode status: see 4.2 Rover / 4.3 Base / 4.4 Static for details.

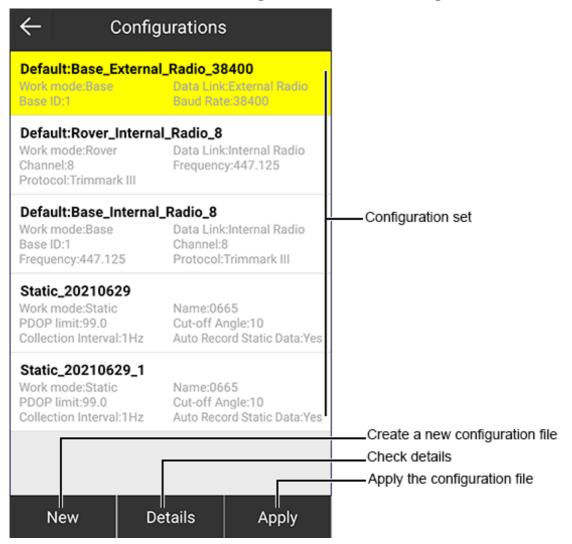


4.6 Configurations

It is used to check all configuration set which includes all work mode settings for the receiver.

In general, default settings can satisfy daily use.

Press main menu **Device** → **Configurations** to enter **Configurations** interface:

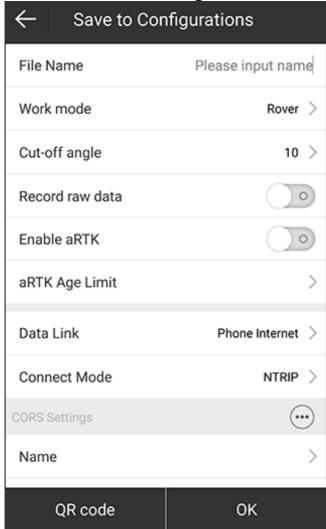




4.6.1 Create a New Configuration File

To create a new configuration file, do the following:

1. Press New. Save to Configurations interface shows:



2. Set related information.

The setting differs in the setting of work mode and data link. See $\underline{4.2}$ Rover / $\underline{4.3}$ Base / $\underline{4.4}$ Static for details.

- 3. **Optional:** To save the configuration file as a QR code and share it to others, do the following:
 - a. Press **QR code**. The QR code is automatically generated.
 - b. Press **Save**, and select the target path. The QR code will save in JPG format.
- 4. Press OK.



4.6.2 Check Details

To check details of a configuration file, do the following:

- 1. Select the target configuration file.
- 2. Press **Details**. **Details** interface shows:

C Details interface shows.	
Title	Content
Work mode	Base
Start Up Mode	Single Point
Base ID	1
PDOP Limit	3.50
Delay Start	60s
Auto start after pow	Yes
Diff Type	RTCM3.2
Cut-off Angle	5
Record raw data	No
Data Link	External Radio
External Serial Port	38400
QR code	ОК

- 3. **Optional:** To save the configuration file as a QR code and share it to others, do the following:
 - a. Press **QR code**. The QR code is automatically generated.
 - b. Press **Save**, and select the target path. The QR code will save in JPG format.
- 4. Press OK.

4.6.3 Apply the Configuration File

To apply the configuration file, do the following:

- 1. Select the target configuration file.
- 2. Press Apply.



4.7 Device Information

Press main menu **Device** → **Device Information** to enter **Device Information** interface:

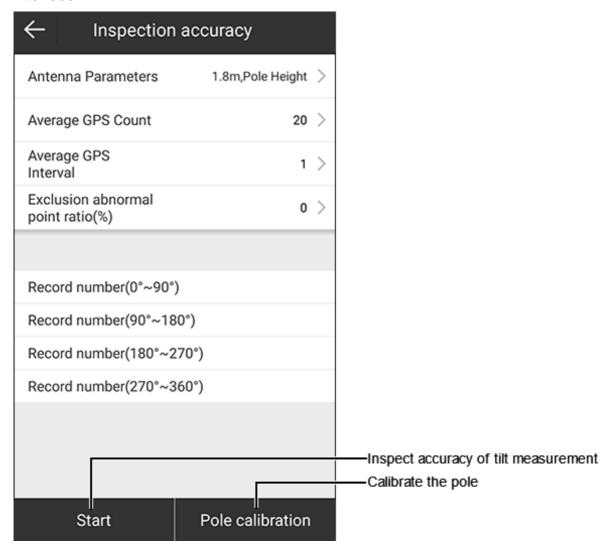
← Device Info	Device Information	
Serial	E30P3A1900047	
Model	E300 Pro	
Hardware Version	V1.1	
BIOS Version	1.05	
Firmware Version	0.22.200922	
GNSS Firmware Ver	6.0Aa03x2	
GNSS Serial	21800417	
OS Version	1.08	
MCU Version	2.61	
Sensor Version	1.3.3	
Work Mode	Rover	Check device info Check network info
Current DataLink	Phone Internet	Check radio info
Device information Network info	Radio info Other	



4.8 Inspection Accuracy

It is used to calibrate the pole and check accuracy of the IMU. And it is required when tilt measurement is enabled and the IMU is used.

Press main menu **Device** → **Inspection Accuracy** to enter **Inspection Accuracy** interface:



For how to enable IMU tilt measurement, see <u>5.1.1</u> Enable IMU Tilt Measurement for details.

4.8.1 Inspect Accuracy of Tilt Measurement

It is used to check if pole calibration is required.

To inspect accuracy of tilt measurement, do the following:

- 1. Set the following parameters:
 - Antenna parameters
 - Average GPS count
 - Average GPS count
 - Average GPS interval
 - Exclusion abnormal point ratios (%)
- 2. Press Start.



- 3. Move the pole $0^{\circ} \sim 90^{\circ}$, and wait the value of **Record number(0°~90°)** turns to **5/5**.
- 4. Move the pole 90° ~ 180°, and wait the value of **Record number(90°~180°)** turns to 5/5.
- 5. Move the pole 180° ~ 270°, and wait the value of **Record number(180°~270°)** turns to **5/5**.
- 6. Move the pole $270^{\circ} \sim 360^{\circ}$, and wait the value of **Record number(270°~360°)** turns to **5/5**.

The result shows as follows:

← Inspection	n accuracy		←	Inspection	accurac	у
Exclusion abnormal point ratio(%)		0 >	Exclusio point rat	n abnormal io(%)		0 >
FIXED			FIXED			
Record number(0°~90	')	5/5	Record r	number(0°~90°	')	5/5
Record number(90°~1	80°)	5/5	Record r	number(90°~18	30°)	5/5
Record number(180°~	270°)	5/5	Record r	number(180°~2	270°)	5/5
Record number(270°~	360°)	5/5	Record r	number(270°~3	360°)	5/5
Test results			Test result	S		
Δplane max(mm)	29	9.827	∆plane r	max(mm)		60.33
Δheight max(mm)		6.63	∆height	max(mm)		43.961
Maximum tilt angle	20°16'15.2	2767°	Maximu	m tilt angle	2	9°21'59.7194"
Min(N) 3439879.1	Max(N) 343987	79.1	Min(N)	3439871.2	Max(N)	3439871.3
Min(E) 359818.998	Max(E) 359819	9.047	Min(E)	359721.779	Max(E)	359721.884
Min(H) 59.997	Max(H) 60	800.0	Min(H)	515.538	Max(H)	515.615
Restart	Pole calibrati	ion	Re	estart	Pole c	alibration

- If the result shows in red, the accuracy is not enough, calibrating the pole is required.
- If not, calibrating the pole is not required.

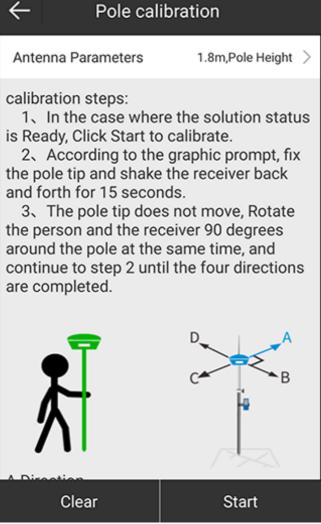


4.8.2 Calibrate the Pole

It is required when tilt measurement is not accurate due to the wear of pole tip or change of the pole.

To calibrate the pole, do the following:

1. To enter **Pole Calibration** interface, press **Pole Calibration**:



- 2. Fix the pole tip and shake the receiver back and forth for 15 s.
- 3. Rotate 90° without moving the pole, and shake the receiver back and forth for 15 s.
- 4. Repeat step 3 until you rotate 360°.

After calibrating the pole, a prompt *Calibrated successfully* shows at the bottom of the interface.

If calibrating the pole fails, find a new area to do calibrating again.



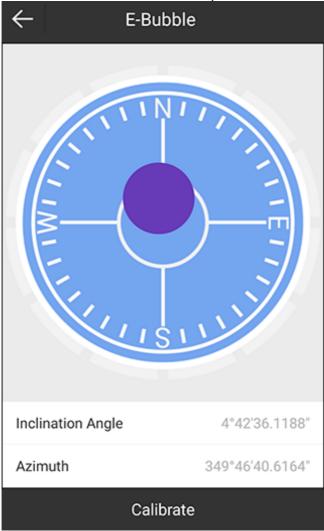
4.9 Calibrate Sensor

It is required when tilt measurement is used and E-bubble is used.

Before calibrating the sensor, to enable E-bubble tilt measurement, press main menu **Device** → **Device Setting**, set tilt survey to **E-Bubble**, and press **OK**.

To calibrate the sensor, do the following:

1. <u>To enter **E-Bubble** interface</u>, press main menu **Device** → **Calibrate Sensor**:

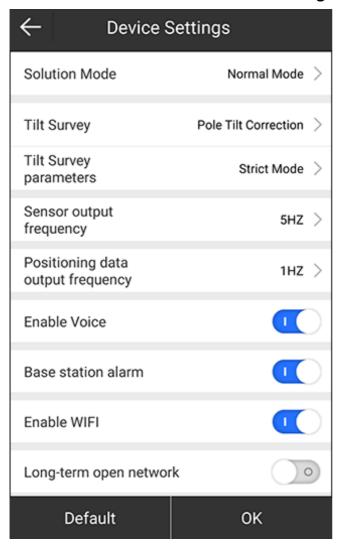


- 2. Put the receiver on a flat place.
- 3. Press **Calibrate**. The E-bubble turns to green.



4.10 Device Settings

Press main menu **Device** → **Device Settings** to enter **Device Settings** interface:



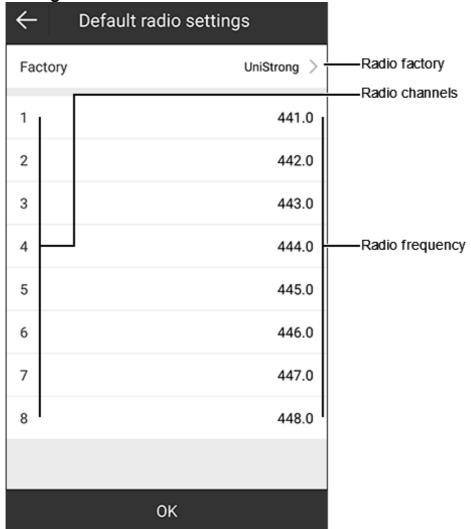
- Solution mode: including normal mode, survey mode and strict mode (in this mode, reliability of solution can be improved.)
- Tilt survey: to enable pole tilt correction (IMU or E-bubble).
- Tilt survey parameters: including normal mode, strict mode or user-defined mode.
- **Positioning data output frequency**: to set the output frequency of the positioning data.
- Enable voice: to select whether to enable receiver voice broadcast function.
- **Base station alarm**: to select whether to remind you when the base station is moved. With it enabled, the rover receiver will broadcast *Base is moved*.
- **Enable WIFI**: to select whether to enable receiver WIFI.
- Long-term open network: to select whether to enable long-term open network. With it enabled, the network initialization will be faster. It is suggested to enable it when a SIM card is used.
- **WIFI share network**: to select whether to share network through WiFi when a SIM card is inserted on the receiver.
- Base coordinate change alert: to select whether to remind you when coordinates
 of the base station changes.



4.11 Default Radio Settings

To set default radio settings, do the following:

 Press main menu Device → Default Radio Settings to enter Default Radio Settings interface:



- 2. To set radio frequency, do one of the following:
 - To use radio frequency of the target factory, press Factory, and select the target factory.
 - To customize radio frequency, press value of the radio frequency, and input a value.
- 3. Press **OK** for confirmation.

4.12 Restart Positioning

It is used to control the receiver to clear the current ephemeris information, so as to initialize OEM board and receive satellites signals again for positioning.

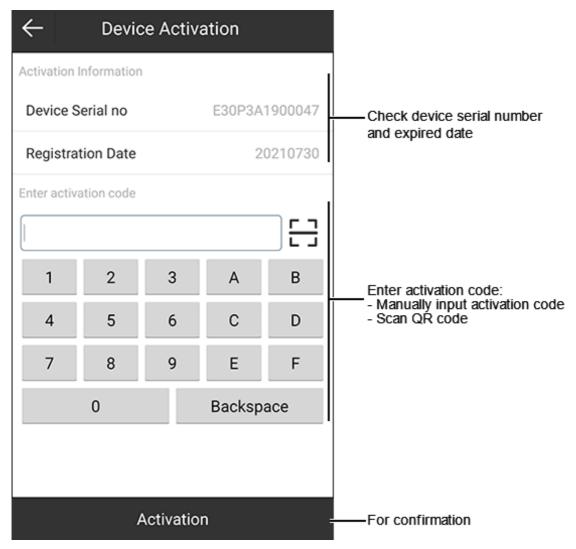
To restart positioning, do the following:

- Press main menu Device → Restart Positioning. A prompt Restart positioning? shows.
- 2. Press **OK** for confirmation.



4.13 Device Activation

Press main menu **Device** → **Device Activation** to enter **Device Activation** interface:

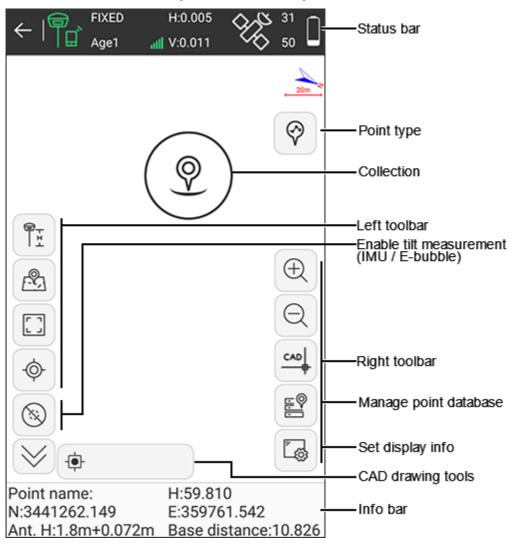




5 Survey

5.1 Point Survey

Press main menu **Survey** → **Point Survey**.



Status bar

Status icon	What it does
←	To exit point survey interface.
	To show the operation mode of the receiver. You can press it to enter Rover / Base / Static mode settings interface. See <u>4.2 Rover / 4.3 Base / 4.4 Static for details.</u>
FIXED Age1	To show the solution status (including single, float, differential and fixed) and the differential delay in real-time.



Status icon	What it does
att	To show the differential signal of the receiver.
H:0.005 V:0.01	H: to show the horizontal accuracy. V: to show the vertical accuracy.
888	To check the current positioning information.
35 43	35: to show the number of used satellites. 45: to show the number of observed satellites.
	To show the battery level of the receiver.
Point type	
Icons	What it does
	Topo point
	Control point
(2)	Quick point
	Automatic point
	Corner point (only when E-bubble is used)
	Tilt point (only when E-bubble is used)



Collection

Icons	What it does
9	To collect coordinates of the current point with tilt survey disabled.
(4)	To start IMU tilt measurement with tilt survey enabled and IMU used. See 5.1.1 Enable IMU Tilt Measurement for details.
	To start E-bubble tilt measurement with tilt survey enabled and E-bubble used.

You can freely drag the collection icon to any position.

Left toolbar

Icons	What it means
	Redraw (to refresh the current displayed data.)
P H	Antenna parameters
	Switch map
	Full map
(\$)	Jump map center
	Tilt survey is disabled.
(IMU tilt survey is enabled. See <u>5.1.1 Enable IMU Tilt Measurement</u> for details.
	E-bubble tilt survey is enabled.
$\langle \rangle$	To collapse icons in the left toolbar.
	To expand icons in the left toolbar.



Icons	What it means
	Display content
BG	CAD background color
	Compass
A B	Offset point calculation
200,000	Equal point calculation
	Coordinate positive calculation
	Forward intersection
	Resection
200	Intersection calculation
840	Two lines angle
→ → →	Great-circle distance
Air	Point line calculation
الم	Coordinate inverse calculation
	Calculator
(তু)	Restart positioning



Icons	What it means
	Static and collect points
	Perimeter and area
XY BL	Coordinates converter
	Screen measurement
TE	CAD text
ZA	Automatic scaling
(PA	Auto jump map center
	Take screen point
Right toolbar	
Icons	What it does
	To zoom out the graphic.
\bigcirc	To zoom in the graphic.
	To enter Points Database interface. See <u>3.5</u> Point Database_for details.
	To set display information. See <u>5.1.3</u> Set Display Information for details.



CAD drawing tools

Icons	What it does
square	To draw a square.
line	To draw a line.
polyline	To draw a polyline.
rect	To draw a rectangle.
rect center	To draw the center of a rectangle.
polygon	To draw a polygon.
circle 2p	To draw a circle by two points.
circle 3p	To draw a circle by three points.
arc	To draw an arc.
point	To draw a point.
Spline	To draw a spline.
Default	To enter Layer Settings interface.



Information bar

- Point name: the point name of collected point.
- N, E, H: the horizontal coordinates (projection point) of the current point.
- Ant. H: the antenna height in survey.
- Base distance: the distance from the current rover station to the base station.

5.1.1 Enable IMU Tilt Measurement



To enable IMU tilt measurement, in left toolbar, press interface:

, and do as the prompt in the

Status	What it means	What to do
Finit MagEnvChange	Magnetic calibration is required.	Take the pole and draw a circle towards the ground.
Finit	Initialization is required.	Shake the pole or walk around.
Inaccurate	The accuracy of tilt measurement is not enough.	Wait.
Inaccurate TiltReject	The tilt angle exceeds 60°.	Make sure the tilt angle is within 0° ~ 60°.
Ready	Tilt measurement is successfully enabled.	Start survey.

5.1.2 Manage Point Database

The operation is the same with operation in main menu **Project**. See <u>3.5</u> Point Database for details.

5.1.3 Set Display Information

It is used to customize display information, including topo point, information bar, and toolbars.

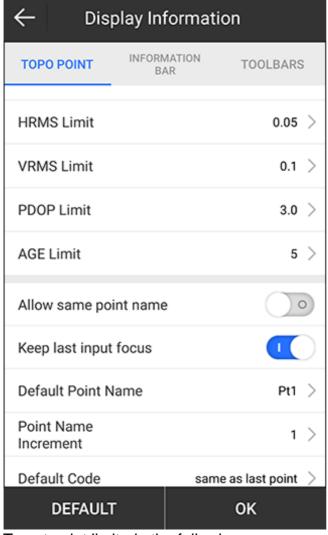


To set display information, do the following:

1. In the main interface of line stakeout, press shows:



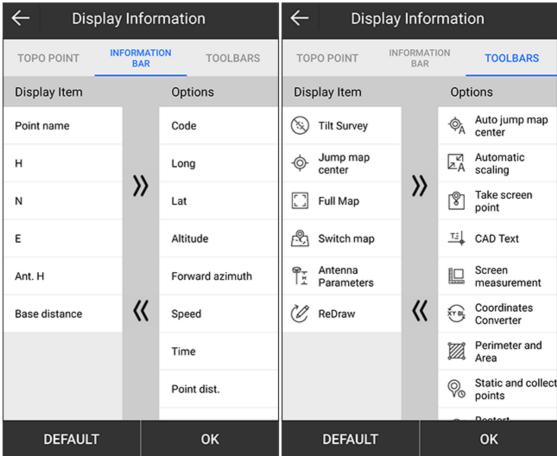
. Display Information interface



- 2. To set point limit, do the following:
 - a. Set recording limit, including solution limit, HRMS limit, VRMS limit, PDOP limit, and AGE limit.
 - b. Select whether to allow the same point name and keep the last input focus.
 - c. Set or select the default point name, and set the increment of the point name, and default code.
 - d. Set or select the average GPS count.



- 3. To customize the information bar / toolbars, do the following:
 - a. To switch to **INFORMATION BAR / TOOLBARS** page, press **INFORMATION BAR / TOOLBARS**:



b. To remove information from **Display Item** list, select the target information in

Display Item list, and press

c. To add information to Display Item list, select the target information in

Options list, and press

4. Optional: To restore settings to default settings, press Default.

5. To save settings, press **OK**.



5.1.4 Start Point Survey

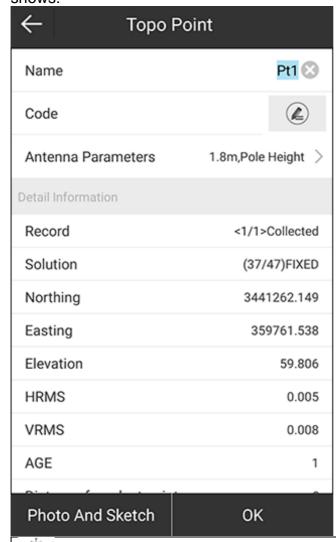
5.1.4.1 Start Survey for a Topo Point

To start survey for a topo point, do the following:

1. Select in the point type area, and press shows:



. Topo Point interface

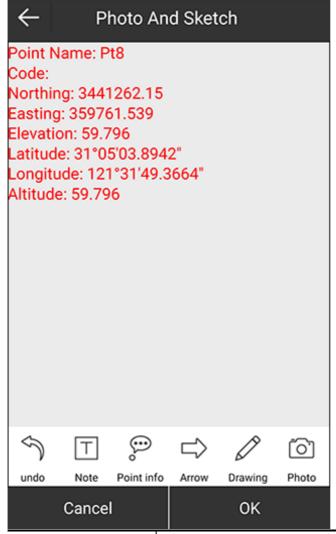


CAUTION: Only when the current point meets the set display limit, **Topo Point** interface shows. Otherwise, a prompt shows.

2. Set point name, code, and antenna parameters, and check detail information.



3. **Optional:** Press **Photo and Sketch** and make an information note on the collected points, including documents, pictures, graphs in **Photo and Sketch** interface:



	Icons	What it does	
5	Undo	To undo and return to the previous step.	
T	Note	To add a note with the customized font size and color.	
0,	Point info	To add point information, including name, code, northing, easting, height, etc. with the customized font size and color.	
\Rightarrow	Arrow	To add arrows with the customized color and style.	
0	Drawing	It is similar to the pencil function in Windows Paint. You can customize the color and thickness.	
$ \bigcirc$	Photo	To directly invoke camera to take a picture to add into information.	
\$\$\$\$	Move	To move any added information.	



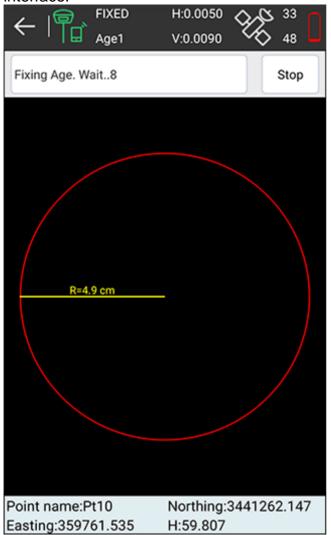
Icons		What it does	
Ĉ	Rotate	To rotate any added information.	
□	Zoom	To zoom in or out any added information.	
	Clear	To clear all information.	

4. To save the topo point, press **OK**.

5.1.4.2 Start Survey for Control Points

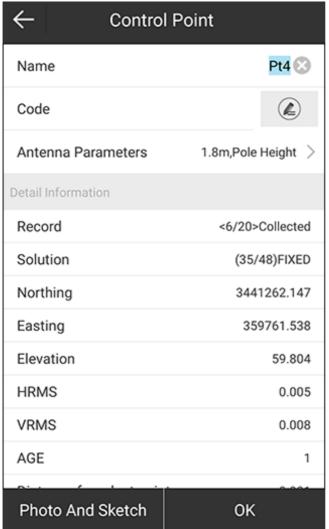
To start survey for control points, do the following:

1. Select in the point type area, and press to enter the following interface:





SurPad automatically starts to collect points every set interval and enters **Control Point** interface until it finishes the set total number:



2. Set point name, code and antenna height. A prompt *Control point report generated, named as xxx, would like to view it now?* shows.



3. **Optional:** To save the control point, press **OK**. The control point report is generated:

100		rement report	
Project ame	(202c10630	ic Information (202c10630 - 202c10630.PD)	
Operator	202010000	., 0)	
Report Time	2021-07-05	2021-07-05 15:44:10	
Antenna Height	1.8715000000000002		
Observation Time	63	63	
Coordinat	te systems p	arameters	
Coordinate System name	te systems p	arameters	
Coordinate system name		arameters WGS-84	
Coordinate	Default Ellipsoid		
Coordinate system name Ellipsoid	Default Ellipsoid Name Semimajor	WGS-84	
Coordinate system name Ellipsoid	Default Ellipsoid Name Semimajor axis	WGS-84 6378137.0	

5.1.4.3 Start Survey for a Quick Point

To start survey a quick point, do the following:



Select in the point type area.



2. Set a point name behind icon

3. Do one of the following:

o To set a code, directly input a code behind icon

○ To select a code that already exists, press 🥝, and select a code.

4. Press . SurPad automatically starts collection after prompt voice and saves the quick point.



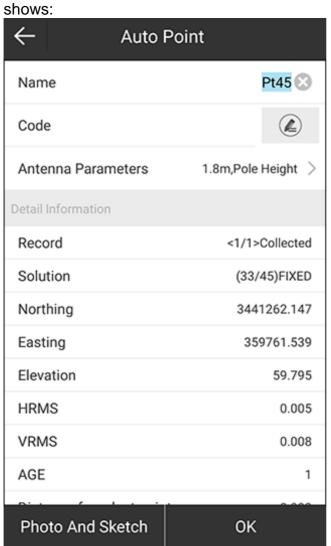
5.1.4.4 Collect Automatic Points

To collect automatic points, do the following:

1. Select in the point type area, and press



. Auto Point interface





2. Set point name, code and antenna height, and click **OK**. SurPad automatically starts to collect point until you interrupt the progress by pressing one of the following:



- Pause: to pause the collecting progress. To resume the collecting, you can press Start.
- o **Stop**: to stop the collecting progress.

5.1.4.5 Start Survey for a Corner Point

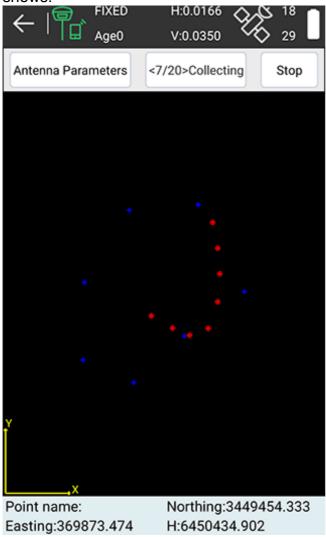
SurPad will automatically calculate coordinates of the pole tip according to the automatically collected 20 points.

It is available only when E-bubble is used.



To start survey for a corner point, do the following:

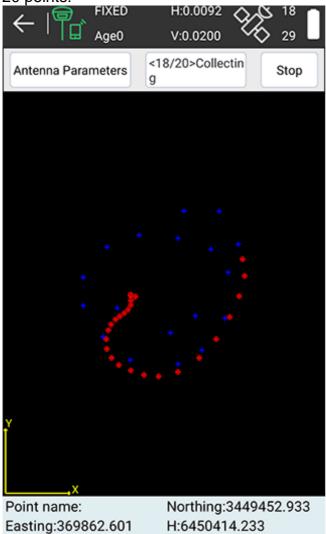
1. Select in the point type area, and press. The following interface shows:



2. **Optional:** To modify antenna parameters, press **Antenna Parameters**, and set antenna parameters.

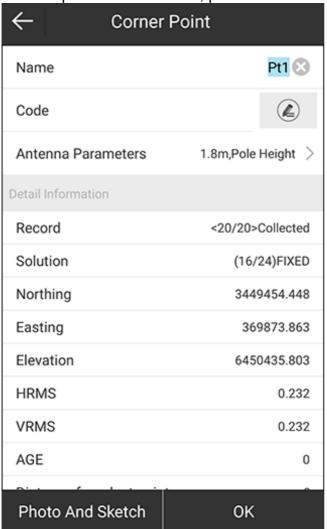


3. Draw circles with the pole without moving the pole tip. SurPad automatically collects 20 points:





4. After 20 points are collected, press **OK** in **Corner Point** interface:





5.1.4.6 Start Survey for a Tilt Point

It is available only when E-bubble is used.

Before starting survey for a tilt point, press



To start survey for a tilt point, do the following:

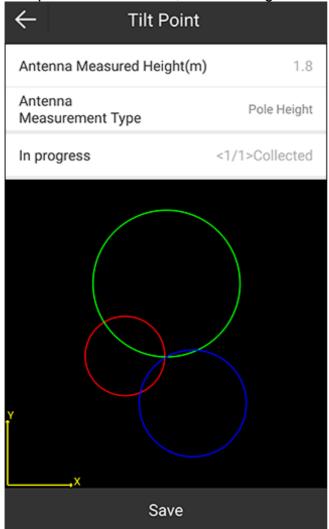
1. Select in the point type area, and press . **Tilt Point** interface shows:



- 2. **Optional:** To modify antenna parameters, press **Antenna Parameters**, and set antenna parameters.
- 3. To start collecting tilt points, press **Start**.
- 4. Incline the pole with the inclined angle greater than 5°. SurPad automatically collects the first tilt point.

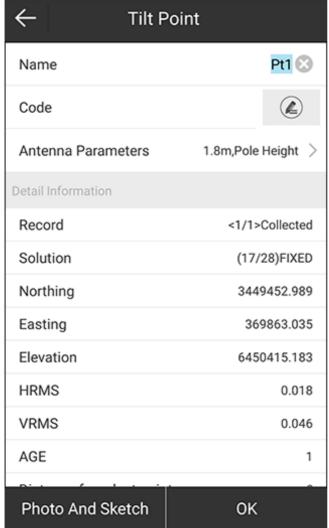


5. Change the inclined direction and repeat step **4** until 3 tilt points are collected. After 3 tilt points are collected, the following interface shows:





6. To save the result, press **Save**. The following interface shows:



7. Press OK.

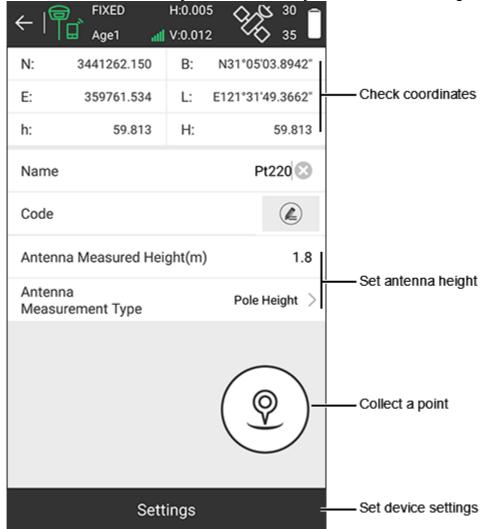


5.2 Detail Survey

It is a simplified mode of point survey for rapid and continuous survey.

To start detail survey, do the following:

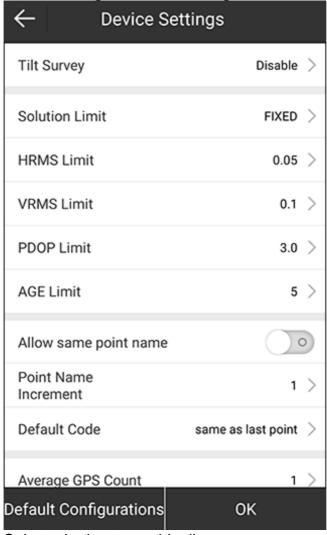
1. Press main menu **Survey** → **Point Survey** to enter the following interface:



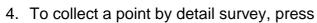
2. Set point name, code and antenna height.



- 3. **Optional:** Set device settings:
 - a. Press Settings. Device Settings interface shows:



- b. Select whether to enable tilt survey.
- c. Set recording limit, including solution limit, HRMS limit, VRMS limit, PDOP limit, and AGE limit.
- d. Select whether to allow the same point name, and set the increment of the point name, and default code.
- e. Select the average GPS count.
- f. Press **OK**.



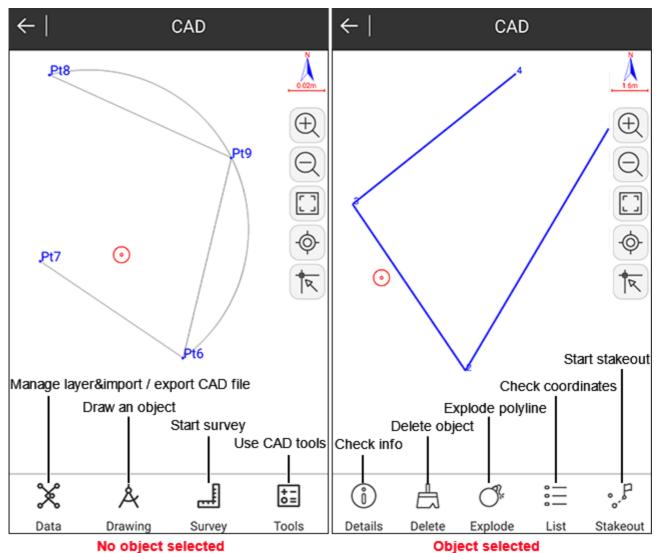




5.3 CAD

It is mainly used to import and edit the existing CAD graphics and stakeout in the existing CAD graphics.

Press Survey \rightarrow CAD to enter CAD interface:



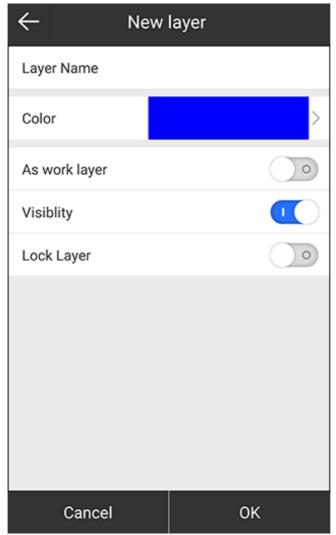
99



5.3.1 Manage the Layer

To manage the layer, do the following:

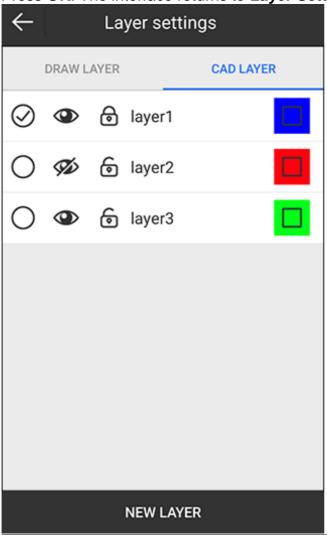
- 1. To add a new layer, do the following:
 - a. To enter New Layer interface, press Data → Layer, and press NEW LAYER:



- b. Input the layer name and set the layer color.
- c. Select the following:
 - Whether to set the layer as the work layer.
 - Whether the layer is visible.
 - Whether to lock the layer.



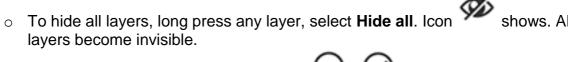
2. Press **OK**. The interface returns to **Layer Settings** interface:



Icons	What it means
\otimes	The layer is the work layer.
0	The layer is not the work layer.
(3)	The layer is visible.
Ø	The layer is not visible.
0	The layer is locked. In the lock status, you cannot select objects of the locked layer.
6	The layer is unlocked.



- 3. **Optional:** Do the following based on your needs:
 - To rename the target layer, select the target layer, long press it, select Rename, and set the layer name.



- To modify the current work layer, press
 Shows
- To modify the lock status, press to unlock the target layer, and press to lock the target layer.
- To modify the layer color, press the color of the target layer, and select a color again.



5.3.2 Import / Export a CAD File

CAD files refer to DXF and DWG files.

To import / export a CAD file, do one of the following:

- To import a CAD file, do the following:
 - a. Press **Data** → **Open**.
 - b. Select the target file path.
- To export a CAD file, do the following:
 - a. Press $Data \rightarrow DXF$ export. DXF export interface shows:



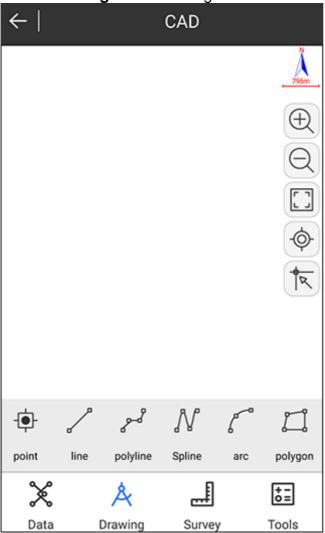
- b. Select the information that you would like to export.
- c. Press Export.



5.3.3 Draw an Object

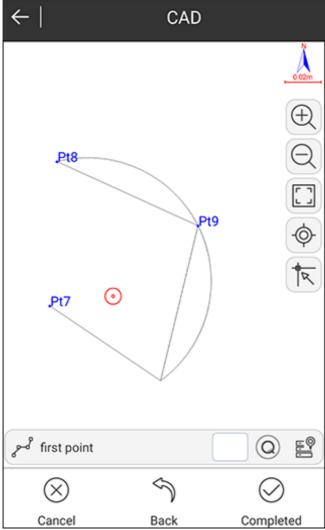
To draw an object, do the following:

1. Press **Drawing**. The following interface shows:





2. Select a shape. The following interface shows:



- 3. Follow tips at the bottom.
- 4. After finishing, press Completed.

5.3.4 Start Survey

It is used to find the intersection point, perform distance offset, division, intersection, lengthening, etc.

Tools		What it does
Int 2 dist To define an intersection by two point and two		To define an intersection by two point and two distance.
×	Int 4 point	To define an intersection by two intersecting lines drawn by four points.
y	Int entity	To define an intersection from object(s).



Tools		What it does
1	Point offset	To define an offset point by a point on the object and offset distance.
11	Dist offset	To copy the object to the set distance.
α_n^{α}	Divide	To divide the object by the input number of partitions.
مرم	Measure	To divide the object by the input fractional length.
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	Invert	To invert the order of target point names on an object.
200	Lengthen	To lengthen the object from the endpoint.

To start survey, do the following:

1. Press **Survey**, and select a survey mode. The following interface shows (taking **Dist offset** as an example):



- 2. Follow tips at the bottom.
- 3. After finishing, press Completed.

5.3.5 Use CAD Tools

With CAD tools, you can achieve the following:

Tools		What it does			
	Delete	To delete the target object.			
\triangle	Angle	To calculate angle.			
مرم	Distance	To calculate points by distance.			



Tools		What it does			
	Area	To calculate area.			
BG	CAD backgroun d color	To modify CAD background color.			
0	Redraw	To refresh the current displayed data.			
ф·	Current position	To show coordinates of the current position.			

To use CAD tools, do the following:

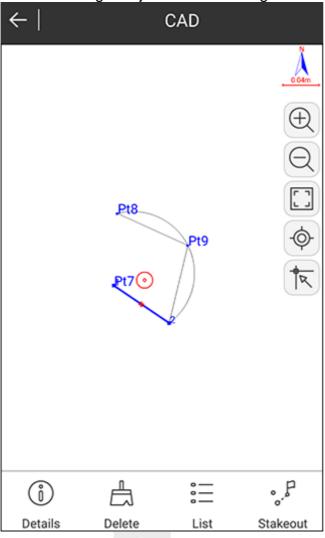
- 1. Press **Tools**, and select the target tool.
- 2. Follow tips at the bottom.
- 3. Press **OK**.



5.3.6 Delete CAD Data

To delete CAD data, do one of the following:

• Select the target object in the drawing window, and press **Delete**:



Press Tools → Delete, select the target object, and press OK.



5.3.7 Check Object Information

To check object information, do the following:

1. Select the target object in the drawing window, and press **Details**. **Object Info** interface shows:

← Obj	ject Info
Entity	line
Layer	0
Color	>
closed	open
Total Length 2D	2331.018m
Total Length 3D	2331.018m
Vertexes	2
center point	
Northing	4093.875
Easting	5180.75
Elevation	0

2. **Optional:** To modify the color of the target object, press **Color**, and select the target color:



- 3. Check the following information:
 - o Entity
 - o Layer
 - Color



- Object type: open or closed
- Total length 2D and 3D
- Vertexes
- Coordinates of the center point

5.3.8 Explode a Polyline

It is used to explode a polyline into several lines.

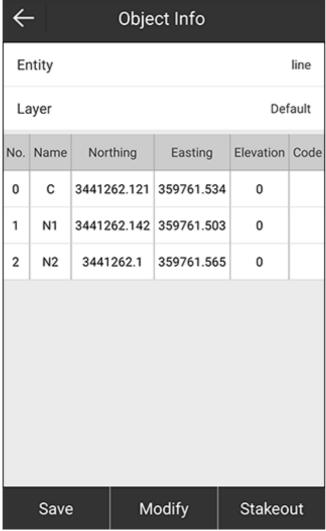
To explode polylines, select the target polyline in the drawing window, and press **Explode**.

5.3.9 Check Coordinates

It is used to check coordinates of the target object, and modify the point name, or start stakeout.

To check coordinates, do the following:

1. Select the target object in the drawing window, and press **List**. The following interface shows:



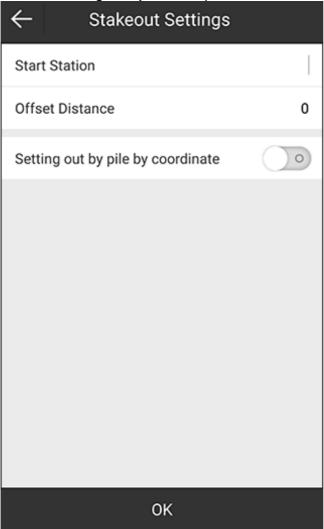
- 2. **Optional:** To modify point name, select the target point, press **Modify**, and modify the name.
- 3. **Optional:** To start stakeout, select the target point, and press **Stakeout**.
- 4. Check coordinates of the target object (including center point).



5.3.10 Start Stakeout

To start stakeout, do the following:

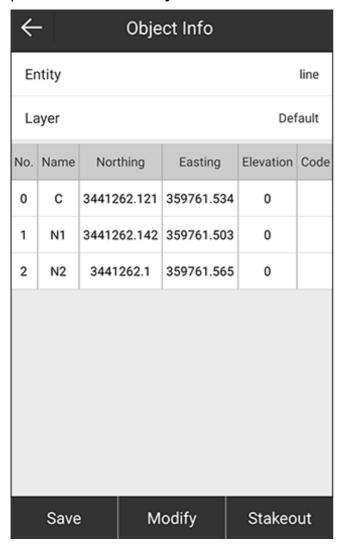
1. Select the target object, and press **Stakeout**. **Stakeout Settings** interface shows:



- 2. Set the start station and offset distance, and select whether to set out by pile by coordinate.
- 3. Press **OK**, and perform stakeout. See <u>5.4</u> Point Stakeout for details.



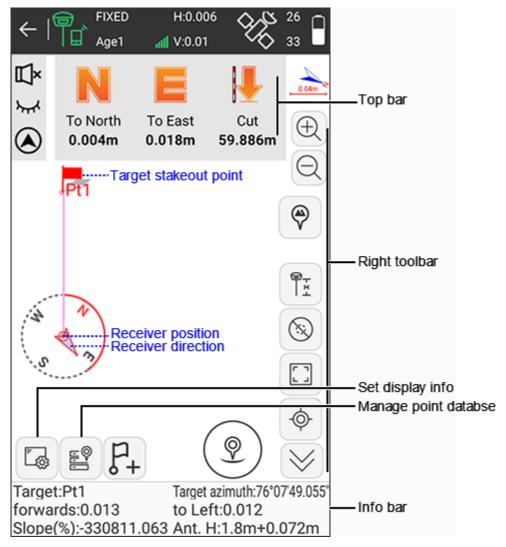
Alternatively, you can start stakeout for points by pressing **List**, select the target point and press **Stakeout** in **Object Info** interface:





5.4 Point Stakeout

To enter the main interface of point stakeout, press $Survey \rightarrow Point Stakeout$, select a target point or add a new point, and press OK:



Top bar

Icons	What it does
N/S	To indicate the distance that the receiver needs to move north / south from the current position to the stakeout point.
E/W	To indicate the distance that the receiver needs to move west / east from the current position to the stakeout point.
↓ / ↑	If the current height is higher than the stakeout point, ↓ shows; if not, ↑ shows.
□ ×	To close the voice prompt of stakeout.
□	To open the voice prompt of stakeout.



Icons	What it does
4	To hide the top bar.
•	To show the top bar.
	To switch to the compass mode.
4	To switch to the distance mode.

Toolbars

Here only icons different from **Point Survey** main interface are listed. About the same icons, please see 5.1 Point Survey for details.

Icons	What it does
P+	To add a new stakeout point.
	To select the last point for stakeout.
·	To select the next point for stakeout.
· F.	To select the point closest to the stakeout point.

Information bar

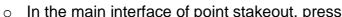
- Target: the name of the stakeout point.
- Target Azimuth: the azimuth from the current point to the target position.
- **Forwards** / **Back**: the distance that the receiver needs to move forwards / back from the current position to the stakeout point.
- **To Left / To Right**: the distance that the receiver needs to move left / right from the current position to the stakeout point.
- **To North** / **To South**: the distance that the receiver needs to move south / north from the current position to the stakeout point.
- **To East / To West**: the distance that the receiver needs to move east / west from the current position to the stakeout point.
- **Slope(%)**: the ratio of the vertical length to the horizontal length.
- Ant.H: the antenna height in survey.



5.4.1 Manage Stakeout Point Database

To manage stakeout point database, do the following:

- 1. To enter **Stake Point** interface, do one of the following:
 - o Press main menu **Survey** → **Point Stakeout**.





← Stake Point						
Со	unt 4	Input name or code			0	
	Name	Northing	Easting	Elevation	Latite	
•	Pt4	10000.000	10000.000	10000.000	N0°05′24	
P	Pt3	1000.000	1000.000	1000.000	N0°00'32	
P	Pt2	100.000	100.000	100.000	N0°00'03	
P	Pt1	10.000	10.000	10.000	N0°00'00	
	Add	Edit	Details	ок		

- 2. Do the following:
 - Add a new stakeout point.
 - Edit a stakeout point.
 - o Check stakeout point information.
 - Import a stakeout point.
 - Delete a stakeout point.
 - Filter a stakeout point.
 - Recover stakeout points.
 - Share a stakeout point.
 - Mark a stakeout point as staked.

The operations are almost the same with operations in **Points Database** interface. See <u>3.5</u> Point Database for details.

Display Information interface

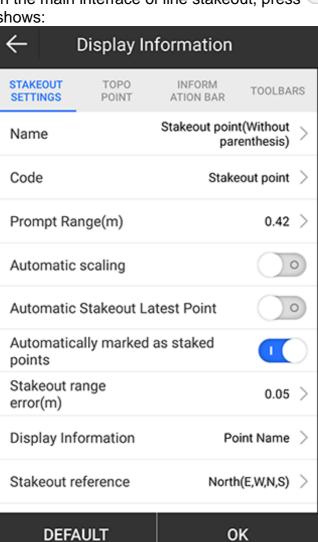


5.4.2 Set Display Information

It is used to customize display information, including stakeout settings, topo point, information bar and toolbars.

To set display information, do the following:

1. In the main interface of line stakeout, press shows:



- 2. Set the following stakeout settings:
 - Name: the name of the stakeout point.
 - Code: to select a code for the stakeout point.
 - o **Prompt range**: to set the target distance triggering precise stakeout.
 - o **Automatic scaling**: to select whether to make the figure automatically display in full screen. Once it is enabled, you cannot zoom in / out the figure.
 - Automatic stakeout latest point: to select whether to automatically stake out the latest point.
 - Automatically marked as staked points: to select whether to automatically mark the selected point as the staked point when the current target distance is less than tolerance.



- o Stakeout reference: to change the display in the top bar (North (E, W, N, S) or forward direction (front, back, left, right)).
- o Voice broadcast: to select whether to enable voice broadcast.
- 3. Set point limit, information bar and toolbars. See 5.1.3 Set Display Information in point survey for details.

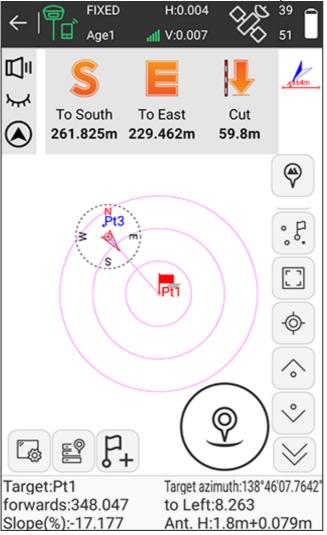
5.4.3 Start Point Stakeout

To start point stakeout, do the following:

1. To select a point for stakeout, do the following:



- a. Press
- b. Select the target point.
- c. Press **OK** to enter stakeout interface.
- 2. Move towards the indicated direction according to information in the information bar. When the target distance is within 3 times of the prompt range, three concentric circles shows, which indicates it enters precise stakeout:

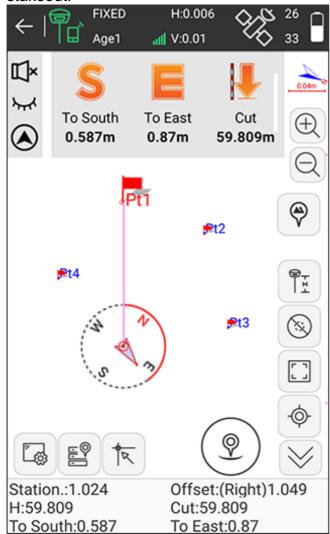


3. Optional: To switch between the adjacent stakeout points in the stakeout point





- 4. After reaching the stakeout point, stake it.
- 5. Press to enter point stakeout database, and select the stakeout point, press ... → Marked as Staked. The target point in point stakeout database turns to blue, and a small red flag shows in the staked point in the main interface of point stakeout:



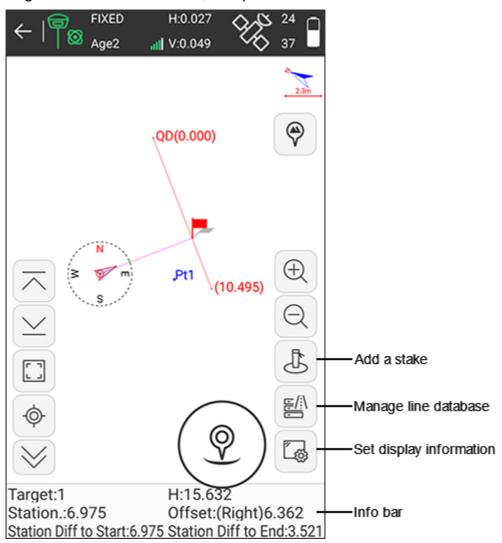
Alternatively, you can enable **Automatically marked as staked points** in display information.



5.5 Line Stakeout

It is the stakeout of the designed line, including line station, left and right offset and elevation control within line.

To enter the main interface of line stakeout, press **Survey** \rightarrow **Line Stakeout**, select the target line or add a new line, and press **OK**:



Information bar

- **Target**: the name of the stakeout line.
- **H**: the height of the current point.
- **Station**: making a perpendicular to the stakeout line through the current receiver position, the start station plus the distance between the foot of perpendicular and the start point.
- Offset: the perpendicular distance from the current position to the target line.
- Station Diff to Start: making a perpendicular to the stakeout line through the current receiver position, the distance from the foot of perpendicular to the start point.
- **Station Diff to End**: making a perpendicular to the stakeout line through the current receiver position, the distance from the foot of perpendicular to the end point.



5.5.1 Manage Line Database

To manage line database, do the following:

- 1. To enter **Lines Database** interface, do one of the following:
 - o Press main menu Survey → Line Stakeout.



o In the main interface of line stakeout, press

 In the main interface of line stakeout, p ← Lines Database 						
No.	Name	Start Station	Length	Azimuth		
1	line1	1.000	0.038	257°47'58.313"		
2	line2	1.038	0.062	43°41'52.9706"		
3	line 3	1.100	0.204	346°06'00.0453"		
Add		Edit	Delet	e OK		

- 2. Do the following:
 - Add a new line.
 - o Edit a line.
 - o Delete a line.
 - o Import a line.
 - o Export a line.

The operations are almost the same with operations in **Points Database** interface. See 3.5 Point Database for details.



5.5.2 Set Stakeout Settings

To set stakeout settings, do the following:

1. To enter **Stakeout Settings** interface, select the target line in line database:



- 2. Select whether to set out by pile by coordinate.
- 3. Do one of the following according to your selection that **Setting out by pile by coordinate** is enabled or not:
 - If it is enabled, select whether to automatically stake the latest point, set station, select a calculation mode, and set interval: Calculation mode:
 - Stakeout by station number: use the start point as the start distance.
 - Stakeout by station distance: use the node as the start distance.
 - Custom mileage offset
 - o If it is not enabled, set cross-section slope (%).
- 4. Press OK.

. Display Information interface

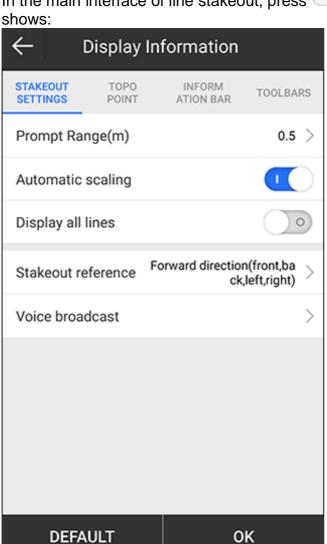


5.5.3 Set Display Information

It is used to customize display information, including stakeout settings, topo point, information bar and toolbars.

To set display information, do the following:

1. In the main interface of line stakeout, press



2. Set the stakeout settings, topo point, information bar and toolbars. See Set Display Information in point stakeout for details.

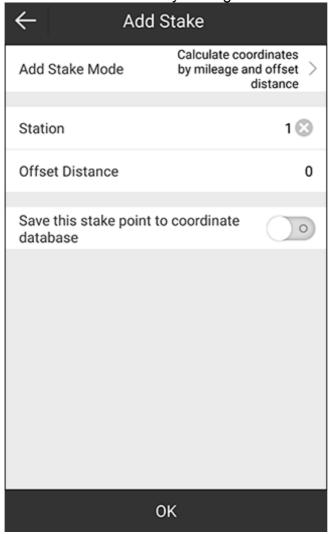


5.5.4 Add a Stake

To add a stake, do the following:

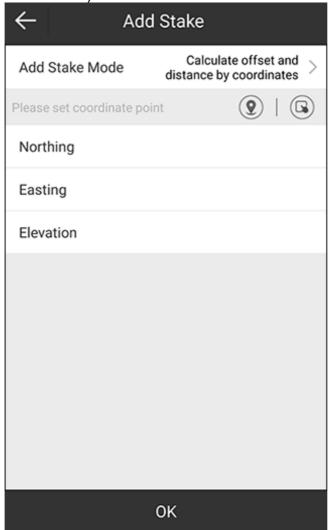


- 1. In the main interface of line stakeout, press
- 2. Select one of the following modes to add stake:
 - o Calculate coordinates by mileage and offset distance

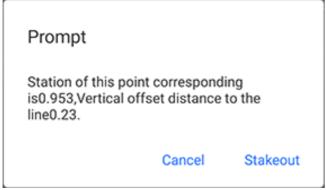




 Calculate offset and distance by coordinates (inputting northing, easting and elevation, search coordinates from the database, or get the current GPS coordinates)



- 3. Set related parameters.
- 4. Press **OK**. A prompt about the calculation result shows:



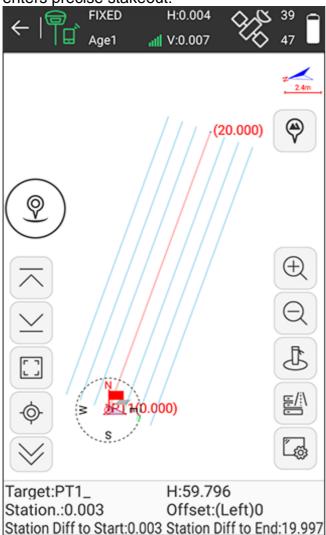
5. Press **Stakeout** to start line stakeout.



5.5.5 Start Line Stakeout

To start line stakeout, do the following:

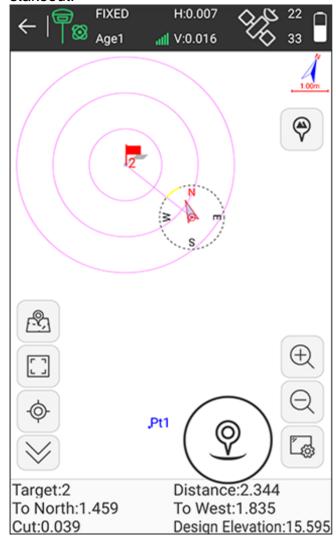
- 1. According to the engineering design, edit the stakeout line in the line database or import a line file.
- 2. Select the target stakeout line and press **OK** to enter line stakeout interface.
- 3. Move towards the indicated direction according to information in the information bar. When the line offsets on both sides are within 3 times of the prompt range, three parallel lines are generated on both sides of the stakeout line, which indicate it enters precise stakeout:

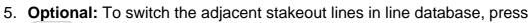




4. **Optional:** To add a stake to the line during stakeout process, see <u>5.5.4</u> Add a Stake for details.

When the target distance is less than 3 times of the prompt range, the system will tale the stake point as center and generate prompt circles to get into precise stakeout:









6. After reaching the stakeout line, stake it.

5.6 GIS Data Collection

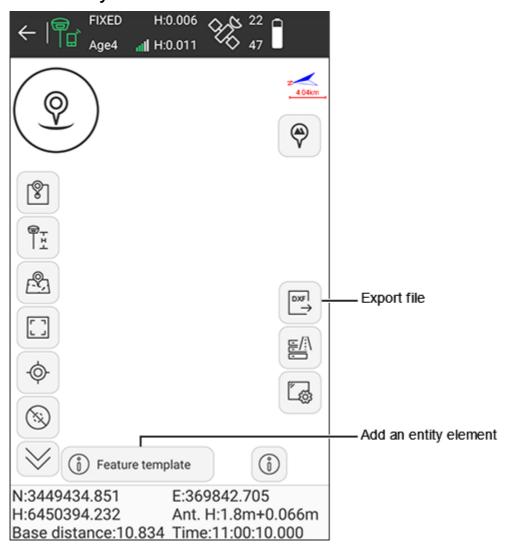
It is used to mark surface features and add labels to them.

The type of a mark surface includes the following:

- Point
- Polyline
- Polygon



Press Survey \rightarrow GIS Data Collection to enter the main interface of GIS data collection:

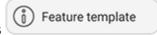




5.6.1 Add an Entity Element

To add an entity element, do the following:

1. To enter Entity Element Management interface, press







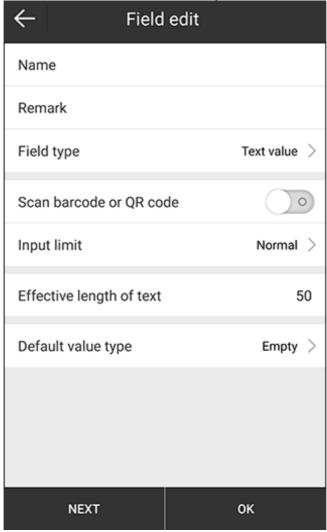
2. To enter **Entity Edit** interface, press **Add**:



- 3. Set an entity name.
- 4. Select a type of the surface feature, and select a style.



- 5. To set label 1 and label 2, do the following:
 - a. To enter Field Edit interface, press Add:



- b. Set a label name, remark.
- c. Select a field type (including integer value, double value, text value, drop-down menu, check box, date, time and file).
- d. Select whether to scan barcode or QR code.
- e. Select a input limit:
 - **Normal**: when the label name is deleted, name will default to 0.
 - Required: name is required.
 - Disabled: name is unchangeable.
 - Hide: the label is hidden in the main interface of GIS Data Collection.
- f. Select the default value type.
- g. Select the target filed for label 1 and label 2.

The interface returns to **Entity Element Management** interface.

6. Select the target entity element, and press ← to return to the main interface.



5.6.2 Start GIS Data Collection

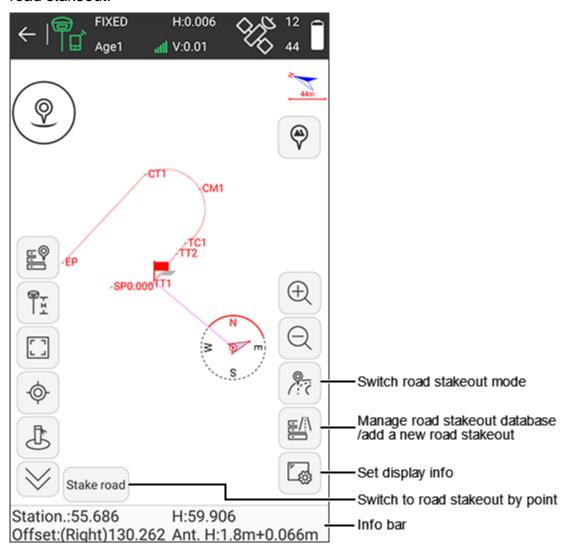
To start GIS data collection, do the following:

- 1. In the main interface of GIS data collection, select a point type, select the target surface feature and draw it.
- 2. To set label details, do one of the following:
 - Press , set the property and press Save.
 - Press , set the property and press Save.
 In this way, you cannot edit label details once you have saved them.

5.7 Stake Road

It is used for stakeout of road, hydraulic engineering, and slope construction.

To enter the main interface of road stakeout, press **Survey** → **Stake Road**, and add a new road stakeout:





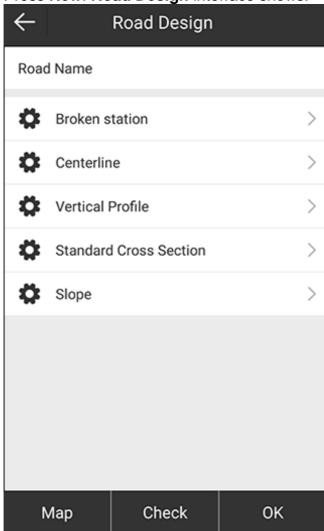
Information bar

- **Station**: making a perpendicular to the stakeout line through the current receiver position, the start station plus the distance between the foot of perpendicular and the start point.
- **H**: the height of the current point.
- Offset: the perpendicular distance from the current position to the target line.
- Ant.H: the antenna height in survey.

5.7.1 Add a New Road Stakeout

To add a new road stakeout, do the following:

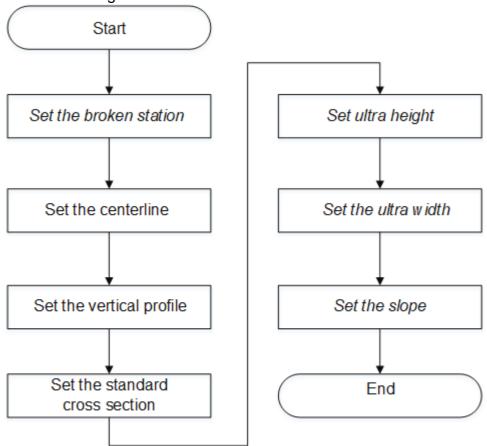
1. Press **New**. **Road Design** interface shows:



2. Set the road name.



3. Do the following:

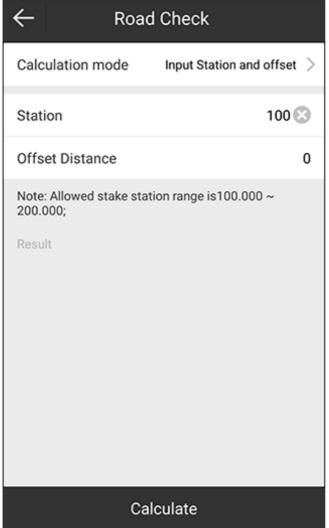


CAUTION: Operations in Italic are optional.

4. **Optional:** To preview the road design, press **Map**.



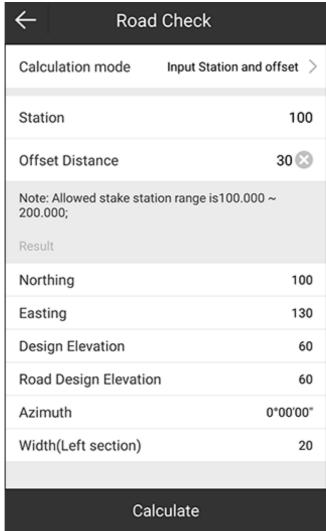
5. **Optional:** To check the road design, press **Check**, and do the following:



- a. Select a calculation mode:
 - Input station and offset
 - Input coordinate
 - Batch export
 - Batch counter calculation
- b. Set station and offset distance.



c. Press Calculate. The result shows in Result area:



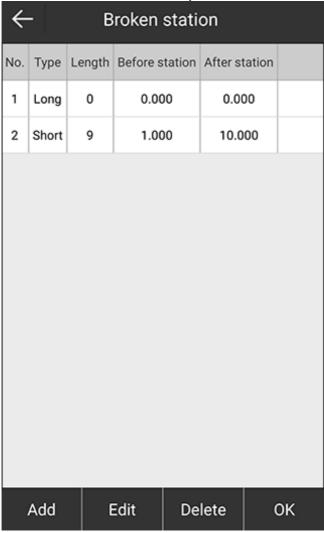


5.7.1.1 Set the Broken Station

It is used to allow broken station without changing all stations when measurement is incorrect or the design changes. That is, you can use new station in the changing place and still old station in other places.

To set the broken station, do the following:

1. To enter Broken Station, press Broken station:



- 2. To add a broken station, press Add.
- 3. Set the following:
 - o **Before station**: the original station of the target point.
 - o After station: the modified station of the target point.
- 4. Optional: To set another broken station, press Next, and repeat step 3.
- 5. Press OK.

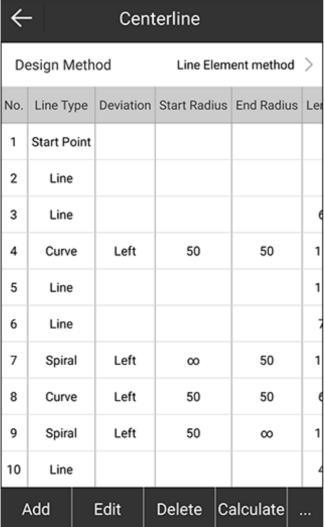


5.7.1.2 Set the Centerline

It is used to define the centerline on the design to the actual road.

To set the centerline, do the following:

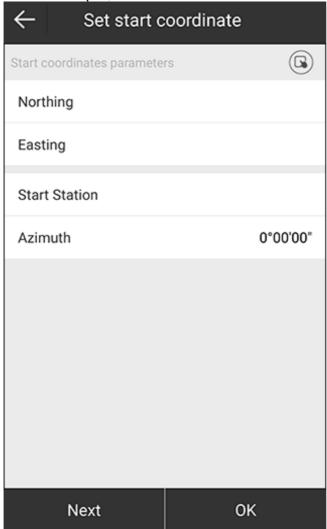
1. To enter **Centerline** interface, press **Centerline**:



- 2. Select a design method:
 - Line element method
 - Intersection method
 - Coordinate element method



3. To add a centerline, press **Add**. Taking the design method **Line element method** as an example, the interface is as follows:



- 4. To set a start coordinate, do one of the following:
 - o To manually input coordinates, set values of **Northing** and **Easting**.
 - To select a point from the point database, press and select the target point.
- 5. Set the start station and azimuth.
- 6. To set end point, press **Next**, or press **OK** → **Add**, and do the following:
 - a. Select a line type:
 - Line
 - Curve
 - Spiral
 - b. Set element parameters.
 - c. Press **OK**.



7. To get coordinates of all set points, press **Calculate**. **Coordinates List** interface shows:

←	Coordinates List			
Name	Station	Northing	Easting	Elevation
SP	0.000	3441262.113	359761.687	0
TT1	5.000	3441262.462	359766.675	0
20.00	20.000	3441273.952	359776.317	0
40.00	40.000	3441289.273	359789.172	0
60.00	60.000	3441304.594	359802.028	0
TC1	72.000	3441313.787	359809.742	0
80.00	80.000	3441320.3	359814.373	0
100.00	100.000	3441339.041	359820.963	0
120.00	120.000	3441358.87	359819.735	0
140.00	140.000	3441376.656	359810.882	0
CM1	150.500	3441384.203	359803.609	0
160.00	160.000	3441389.59	359795.801	0

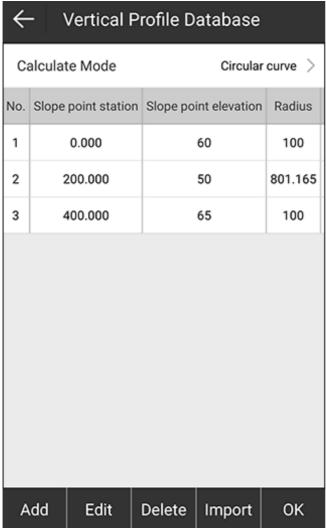
8. To return to **Road Design** interface, press ← twice in the upper left corner.



5.7.1.3 Set the Vertical Profile

To set the vertical profile, do the following:

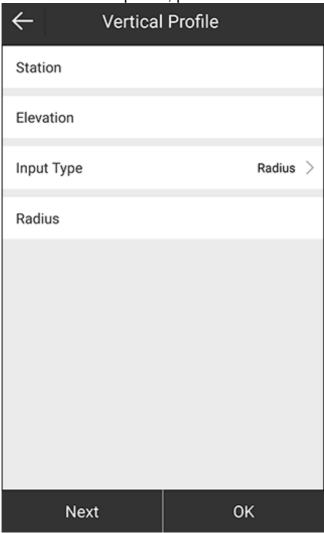
1. To enter Vertical Profile Database interface, press Vertical Profile:



- 2. Select a calculation mode:
 - o Circular curve
 - o Parabola



3. To add a vertical profile, press **Add**:



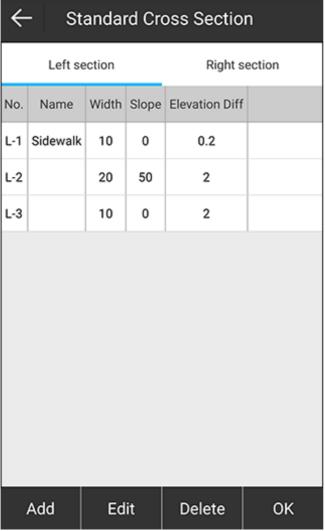
- 4. Set the station and elevation.
- 5. Select an input type (radius and spiral length), and set radius or spiral length.
- 6. Optional: To set another vertical profile, press Next, and repeat step 4 and 5.
- 7. Press **OK**.



5.7.1.4 Set the Standard Cross Section

To set the standard cross section, do the following:

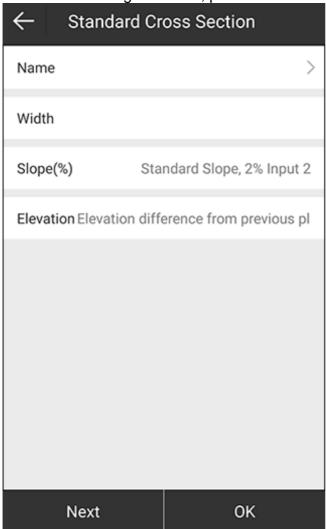
1. To enter Standard Cross Section interface, press Standard Cross Section:



2. Select setting left section or right section.



3. To add a left or right section, press **Add**.



- 4. Set a name.
- 5. Set the following:
 - o Width: the horizontal length.
 - o **Slope** (%): the ratio of vertical length to horizontal length.
 - o **Elevation**: the distance between the road and curb.
- 6. **Optional:** To set copy setting to right-section / left-section, switch to related page, and press **Symmetry**.
- 7. Press OK.

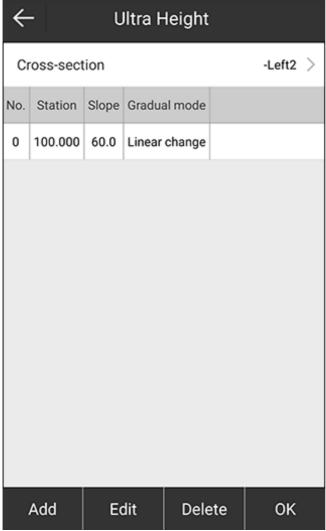


5.7.1.5 Set the Ultra Height

It is used to change the slope of the cross section.

To set the ultra height, do the following:

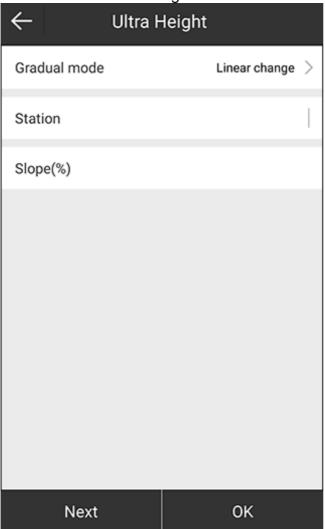
1. To enter **Ultra Height** interface, press **Ultra Height**:



2. Select the cross-section.



3. Press Add. The following interface shows:



- 4. Select a gradual mode:
 - o Linear change:
 - o Three parabola:
- 5. Set the station and slope.
- 6. Optional: To set another ultra height, press Next, and repeat step 4 and 5.
- 7. Press **OK**.



5.7.1.6 Set the Ultra Width

It is used to change the length of the cross section.

To set the ultra width, do the following:

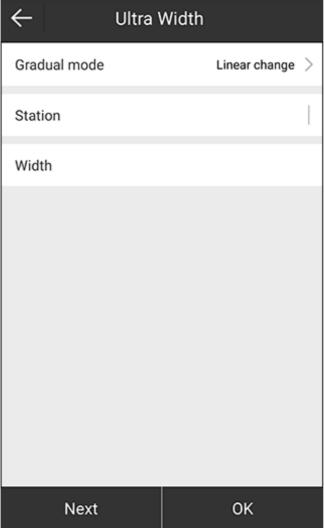
1. To enter Ultra Width interface, press Ultra Width:



2. Select the cross-section.



3. Press **Add**. The following interface shows:



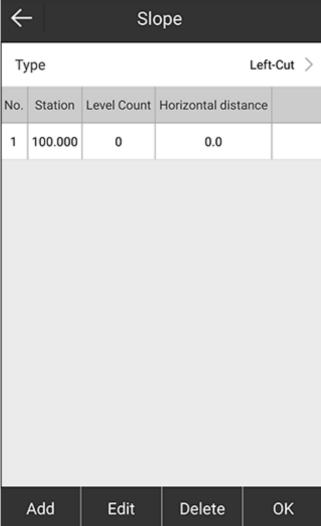
- 4. Select a gradual mode:
 - Linear change:
 - o Three parabola:
 - o Four parabola:
- 5. Set the station and width.
- 6. Optional: To set another ultra width, press Next, and repeat step 4 and 5.
- 7. Press **OK**.



5.7.1.7 Set the Slope

To set the slope, do the following:

1. To enter **Slope** interface, press **Slope**:



- 2. Select a slope type:
 - o Left-cut
 - o Left-fill
 - o Right-cut
 - o Right-fill

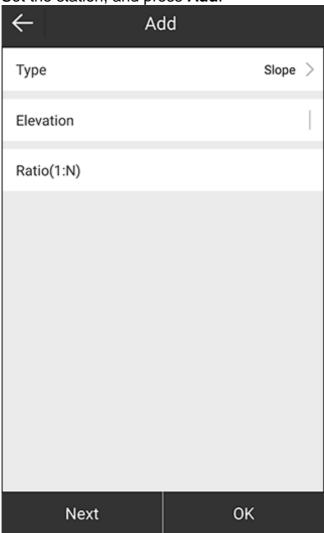


3. Press Add. Add Slope interface shows:

Add Slope						
St	Station					
No.	Туре	Height/Width	Ratio/Slope	Width		
1	Slope	10	1:10	100		
2	Platform	19	5%	19		
		- 11.				
	Add	Edit	Delete	C	K	



4. Set the station, and press **Add**:



- 5. Select a type (slope or platform).
- 6. Set elevation and ratio(1:N).
- 7. **Optional:** To set another slope, press **Next**, and set related items. The interface returns to **Add Slope** interface.
- 8. Select the target type, and press **OK**. The interface returns to **Slope** interface.
- 9. Select the target slope, and press **OK**.



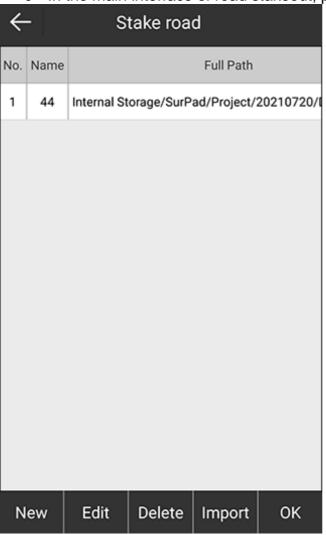
5.7.2 Manage Road Stakeout Database

To manage road stakeout database, do the following:

- 1. To enter **Stake Road** interface, do one of the following:
 - If it is your first time to start road stakeout, press main menu Survey → Stake Road.



In the main interface of road stakeout, press



- 2. Do the following:
 - Add a new road stakeout.
 - Edit a road stakeout.
 - Delete a road stakeout.
 - Import a road stakeout.

5.7.3 Switch the Road Stakeout Mode

Road stakeout mode includes the following:

- Centerline stakeout
- Cross-station stakeout: it is to stake out the designed road on the drawing to the corresponding ground by marking the excavation line and filling line for construction.



To switch the road stakeout mode, do one of the following in the main interface of road stakeout:





To switch to cross-station stakeout, press



5.7.4 Set Display Information

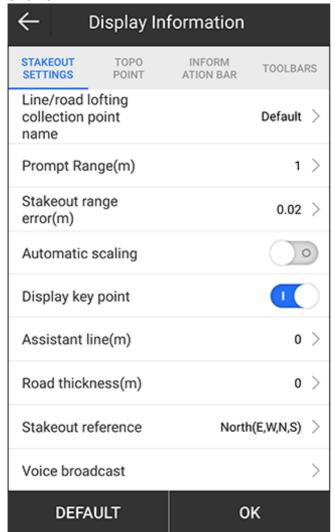
It is used to customize display information, including stakeout settings, topo point, information bar, and toolbars.

To set display information, do the following:

1. In the main interface of road stakeout, press shows:



. Display Information interface



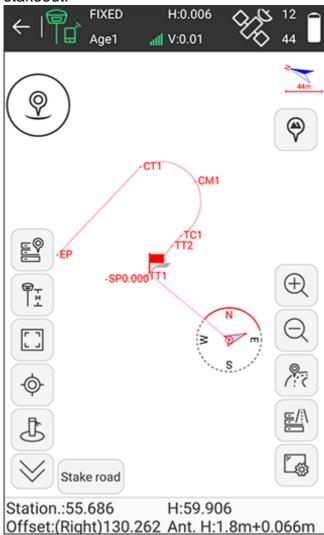
2. Set stakeout settings, topo point, information bar and toolbars. See 5.4.2 Set Display Information in point stakeout for details.



5.7.5 Start Road Stakeout

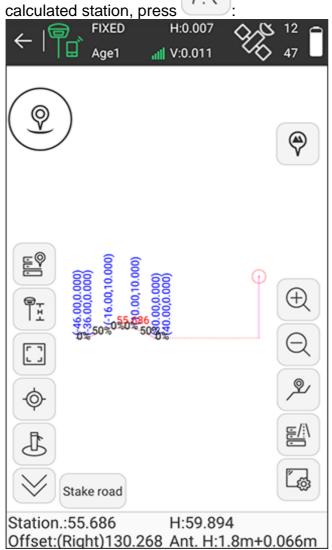
To start road stakeout, do the following:

- 1. According to the engineering design, edit the stakeout road in road stakeout database.
- 2. Select the target stakeout road and press **OK** to enter the main interface of road stakeout.





3. Optional: To view slope graph in the range of the current station based on the



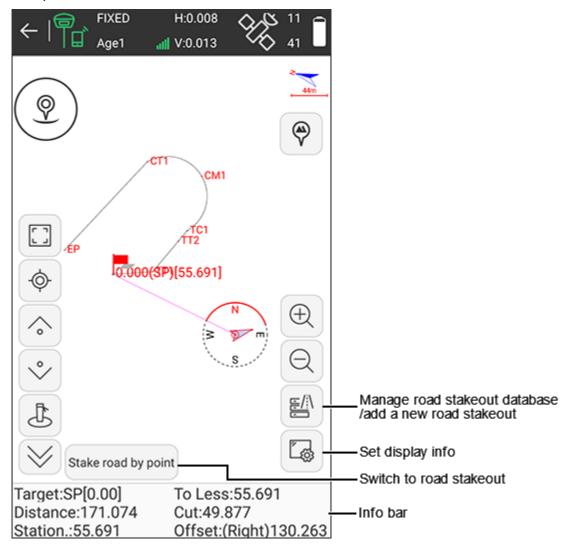
- 4. Move towards the indicated direction according to information in the information bar.
- 5. After reaching the stakeout road, stake it.



5.8 Stake Road by Point

It is used for continuous stakeout of specific stakes with fixed stake distance like 20 / 50 / 100 or with specific stake number as construction required.

To enter the main interface of road stakeout by point, press **Survey** → **Stake Road by Point**, add a new road stakeout / select a road stakeout, press **OK**, set stakeout settings, and press **OK**:



Information bar

- Target: the name of the stakeout road.
- To More / To Less: the distance from the current point to target peg. To More
 means the station of the target point is greater than the station of the current point.
 To Less means the station of the target point is less than the station of the current
 point.
- **Distance**: the distance between the receiver and the stakeout point.
- Cut / Fill: if Cut shows, the current position is higher than target point; if Fill shows, the current position is lower than target positions.
- **Station**: making a perpendicular to the stakeout line through the current receiver position, the start station plus the distance between the foot of perpendicular and the start point.

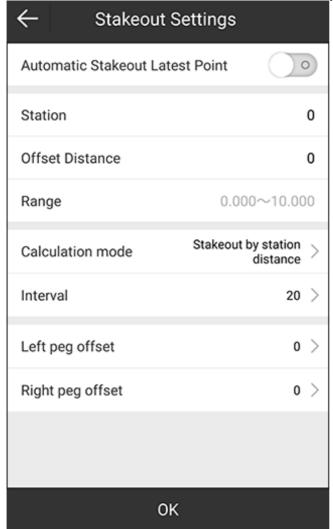


• Offset: the perpendicular distance from the current position to the target line.

5.8.1 Set Stakeout Settings

To set stakeout settings, do the following:

 To enter Stakeout Settings interface, press Survey → Stake Road by Point, add a new road stakeout / select a road stakeout, press OK:



- 2. Select whether to automatically stake out the latest point.
- 3. Set station, offset distance and range.
- 4. Select a calculation mode:
 - Stakeout by station number
 - Stakeout by station distance
- 5. Set interval.
- 6. Set left peg offset and right peg offset.
- 7. Press OK.

5.8.2 Add a New Road Stakeout

To add a new stakeout road, see 5.7.1 Add a New Road Stakeout for details.

5.8.3 Manage Road Stakeout Database

To manage road stakeout database, see <u>5.7.2</u> Manage Road Stakeout Database for details.



5.8.4 Set Display Information

To set display information, see <u>5.4.2</u> Set Display Information in point stakeout for details.

5.8.5 Start Road Stakeout by Point

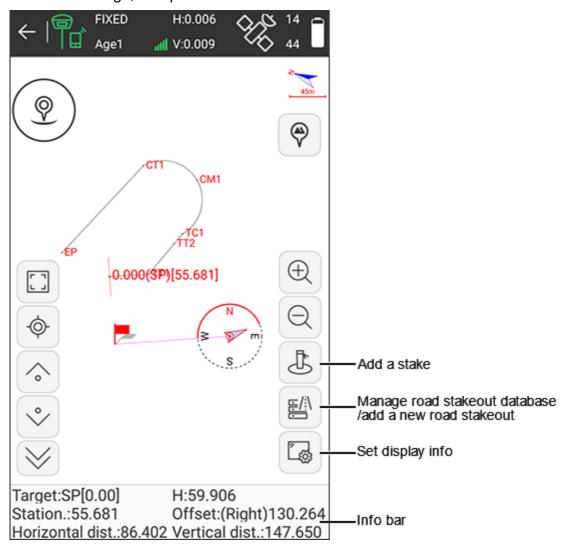
To start road stakeout by point, do the following:

- 1. Select the target stakeout road and press **OK**.
- 2. Set stakeout settings, and press **OK** to enter the main interface of road stakeout by point.
 - See <u>5.8.1</u> Set Stakeout Settings for details.
- 3. Move towards the indicated direction according to information in the information bar.
- 4. After reaching the stakeout point of the road, stake it.

5.9 Cross Section Measurement

Cutting a road into slices creates many parallel cross sections. This operation is used to mark the position of cross sections for line engineering and hydraulic engineering.

To enter the main interface of cross section measurement, press **Survey** → **Cross Section Measurement**, add a new road stakeout / select a road stakeout, press **OK**, set stakeout settings, and press **OK**:





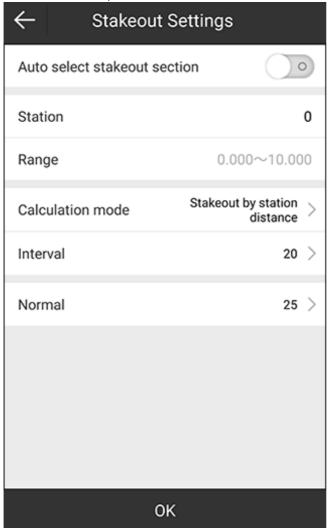
Information bar

- Target: the name of the current stakeout road.
- **H**: the elevation of the current receiver position.
- **Station**: making a perpendicular to the stakeout line through the current receiver position, the start station plus the distance between the foot of perpendicular and the start point.
- Offset: the perpendicular distance from the current position to the target line.
- **Horizontal dist.**: making a perpendicular to the cross section through the current receiver position, the distance from the foot of perpendicular to the intersection point of the cross section and stakeout line.
- **Vertical dist.**: making a perpendicular to the cross section through the current receiver position, the distance from the foot of perpendicular to the current position of the receiver.

5.9.1 Set Stakeout Settings

To set stakeout settings, do the following:

 To enter Stakeout Settings interface, press Survey → Cross Section Measurement, add a new road stakeout / select a road stakeout, press OK:



- 2. Select whether to automatically stake out the latest point.
- 3. Set station.



- 4. Select a calculation mode:
 - Stakeout by station number
 - Stakeout by station distance
- Set interval.
- 6. Set the length of normal (the distance between the centerline and the ends of cross section).
- 7. Press OK.

5.9.2 Add a New Stakeout Road

To add a new stakeout road, see 5.7.1 Add a New Road Stakeout for details.

5.9.3 Manage Road Stakeout Database

To manage road stakeout database, see <u>5.7.2</u> Manage Road Stakeout Database for details.

5.9.4 Set Display Information

To set display information, see <u>5.4.2</u> Set Display Information in point stakeout for details.

5.9.5 Start Cross Section Measurement

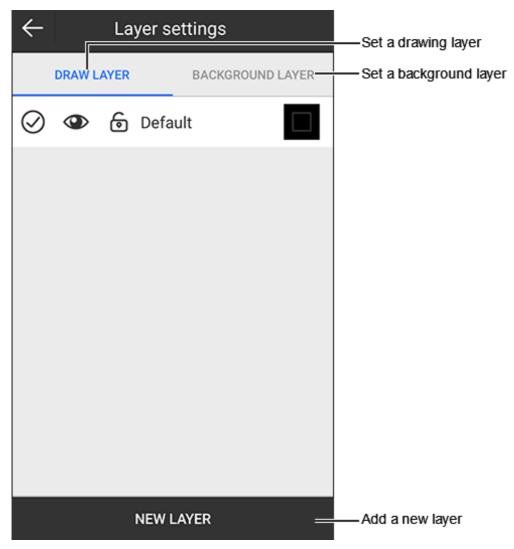
To start cross section measurement, do the following:

- 1. According to the engineering design, edit the stakeout road in road stakeout database.
- 2. Select the target stakeout road and press **OK**.
- 3. Set stakeout settings, and press **OK** to enter the main interface of cross section stakeout.
 - See <u>5.9.1</u> Set Stakeout Settings for details.
- 4. Move towards the indicated direction according to information in the information bar.
- 5. **Optional:** To add a stake to the cross section during stakeout process, see <u>5.5.4</u> Add a Stake in line stakeout for details.
- 6. After reaching the stakeout road, stake it.



5.10 Layers Settings

The main interface is as follows:



5.10.1 Set Drawing Layer

See <u>5.3.1</u> Manage the Layer for details.



5.10.2 Set Background Layer

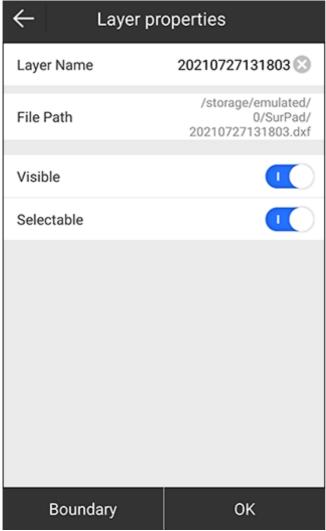
To set background layer, do the following:

1. Switch to **BACKGROUND LAYER** page:





2. Press **ADD**, and select the target format and file. **Layer Properties** interface shows:



Supported file format:

AutoCAD file: *.dxf, *.dwg

Shape file: *.shpLandXML: *.xml

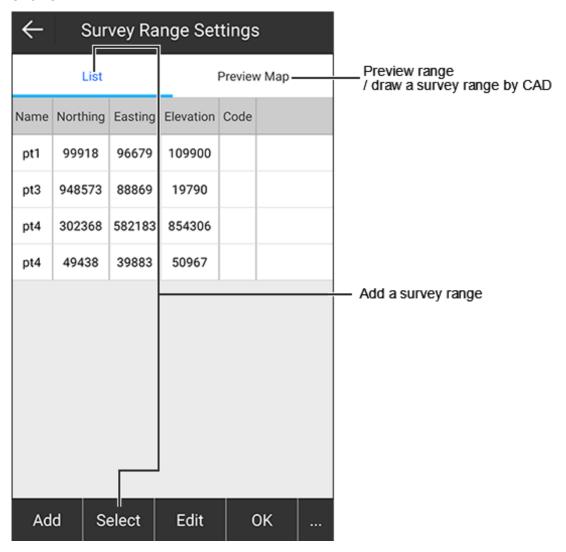
- 3. Edit properties of the target layer.
- 4. **Optional:** To check the layer boundary, press **Boundary**.
- 5. Do the following in **BACKGROUND LAYER** page based on your needs:
 - o To edit the target layer, select the target layer, and press **EDIT**.
 - o To move the target layer down, select the target layer, and press MOVE UP.
 - To move the target layer up, select the target layer, and press MOVE DOWN.
 - o To delete the target layer, select the target layer, and press **DELETE**.



5.11 Survey Range Settings

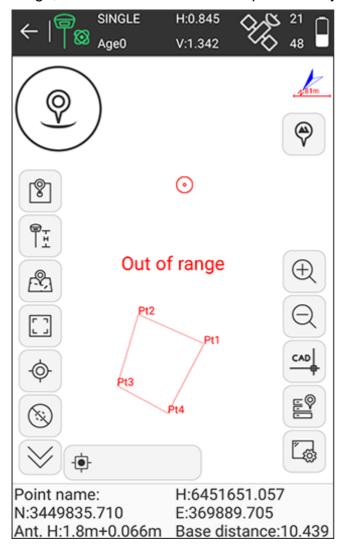
It is used to set the survey range and make sure all measured points are within the range. When the current point exceeds the range, a prompt shows.

Press main menu Survey \rightarrow Survey Range Settings. Survey Range Settings interface shows:





After adding or drawing a survey range, to check if the current point exceeds the set range, enter the main interface of point survey:

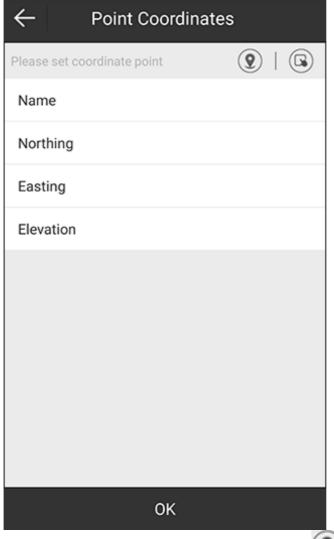




5.11.1 Add a Survey Range

To add a survey range, do the following:

- 1. In **List** page, do one of the following:
 - o Press **Add**, and do one of the following to set coordinates of a point:



- To use the current GPS coordinates, press and set antenna parameters.
- To select a point from the point database, press and select the target point.
- To manually input coordinates, set values of Northing, Easting and Elevation.
- o To select points in batch mode, press **Select**, and select the target points.
- 2. Press OK.

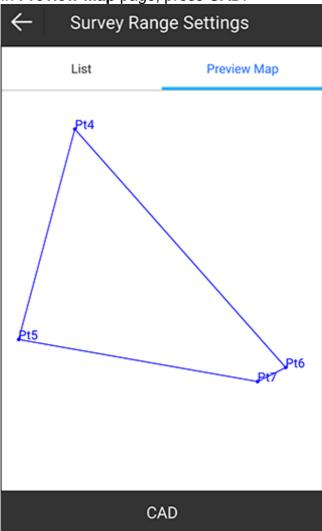
Alternatively, you can press **Select** in **List** page, and select points from the point database.



5.11.2 Draw a Survey Range by CAD

To draw a survey range by CAD, do the following:

1. In **Preview Map** page, press **CAD**:



- 2. Do one of the following:
 - Select to load the last CAD drawing.
 - o Draw a range by CAD drawing tools.
- 3. Select the drawing, and press **OK** to exit CAD. The interface returns to **Preview Map** page.

CAUTION: Selecting the drawing is required. Otherwise, drawing a survey range by CAD will fail.

4. Switch to **List** page, press **OK**.

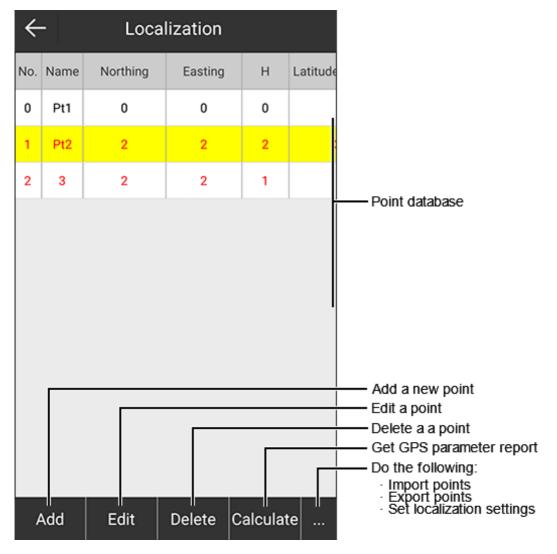


6 Tools

6.1 Localization

In general, the output data of the receiver is WGS-84 latitude and longitude coordinates. The coordinates need to be converted to local coordinates, which requires SurPad to calculate and configure coordinate conversion parameters. Localization is the main tool to achieve this.

Press main menu **Tools** → **Localization** to enter **Localization** interface:

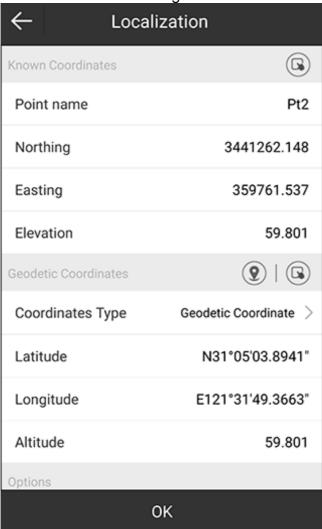




6.1.1 Add a Localization Point

To add a localization point, do the following:

1. Press **Add**. The following interface shows:



- 2. To set coordinates of a known point, do one of the following in **Known Coordinates** area:
 - To select a point from the point database, press and select the target point.
 - To manually input coordinates, set point name and values of Northing, Easting and Elevation.



- 3. To set WGS84 geodetic coordinates, do one of the following in **Geodetic Coordinates** area:
 - To use the current GPS coordinates, press , set antenna parameters, and a point name.
 - To select a point from the point database, press and select the target point.
 - To manually input the coordinates, select one of the following coordinate types and set coordinates:
 - Geodetic coordinate: including latitude, longitude and altitude.
 - Local coordinate: including northing, easting and elevation.
- 4. Select whether to enable the horizontal control and vertical control.
- 5. Press OK.

6.1.2 Edit a Localization Point

To edit a localization point, do the following:

- 1. Select the target point, and press **Edit**.
- 2. Edit parameters of this point.

 See <u>6.1.1</u> Add a Localization Point for details.

6.1.3 Delete a Localization Point

To delete a localization point, do the following:

- 1. Select the target point, and press **Delete**. A prompt *Are you sure to delete this record?* shows.
- 2. Press OK.

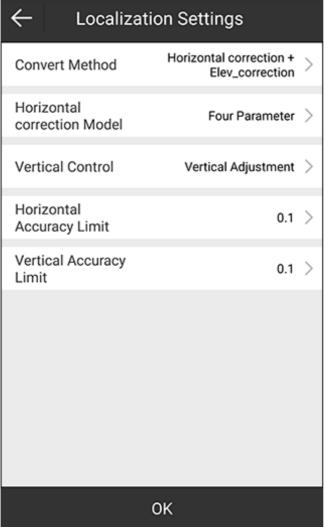
All data about this point is deleted from the point database.



6.1.4 Set Localization Settings

To set localization settings, do the following:

1. To enter **Localization Settings**, press ... → **Options**:



- 2. Select a conversion method:
 - Horizontal correction + Elev_correction
 - Horizontal + Vertical Adjustment
 - Seven parameter + Horizontal correction + Elev correction
 - Seven Parameter
- 3. Optional: If the conversion method is set as Horizontal correction + Elev_correction or Seven parameter + Horizontal correction + Elev_correction, select a horizontal correction model:
 - Horizontal Adjustment
 - Four Parameter
- 4. Optional: If the conversion method is set as Horizontal correction + Elev_correction or Seven parameter + Horizontal correction + Elev_correction, select a vertical control mode:
 - Automatic Selection
 - Weighted Average
 - Plane Fitting
 - Surface Fitting



Vertical Adjustment

5. Set horizontal accuracy limit and vertical accuracy limit. If points in the coordinate point database exceed the set horizontal accuracy limit, information about these points turns red:

← Localization					
No.	Name	Northing	Easting	н	_atitude
0	Pt1	0	0	0	
1	Pt2	2	2	2	:
2	3	2	2	1	
Å	Add	Edit	Delete	Calculate	

6.1.5 Get the GPS Parameter Report

After all points participated in the parameter calculation have been add, you can get the GPS parameter report.



To get the GPS parameter report, do the following:

1. Press Calculate. GPS Parameters Report interface shows:

← GPS Parameters Report				
Ellipsoid Parameter				
Ellipsoid Name	WGS 84			
Semimajor axis	6378137			
1/f	298.257			
Projections Parameter				
Projections Mode	UTM			
Central Meridian	E123°00'00"			
Northing constant	0			
Easting constant	500000			
Scale Factor	0.9996			
Projection Height	0			
Latitude of Origin	N0°00'00"			
Save	Apply			

- 2. **Optional:** To export the report, press **Save** and select the target storage path.
- 3. To refresh data in the coordinate point database, press **Apply**.

To check whether the calculation results are accurate or reliable, find known points to check the coordinate accuracy. See <u>5.1</u> Point Survey for details.

6.1.6 Import Localization Points

It is used to import localization points in *.cot, *.loc, *.fou, *.tfou. formats.

To import a localization point, do the following:

- 1. Press ... → Import.
- 2. Select the target storage path, and press **OK**.

6.1.7 Export Localization Points

It is used to export localization points in *.cot format for later use.

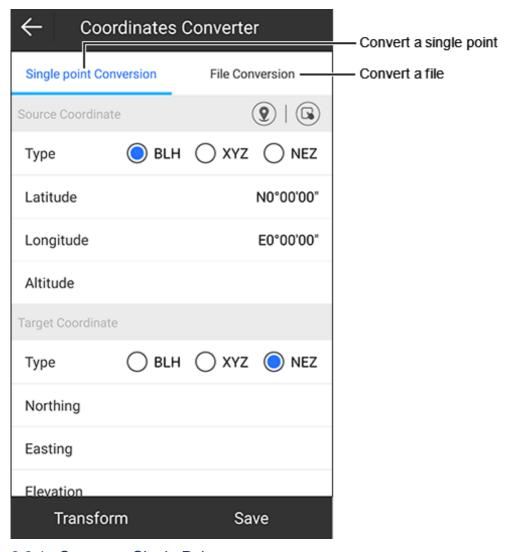
To export a localization point, do the following:

- 1. Press $\dots \rightarrow Export$.
- 2. Select the target storage path, and press **Export**.



6.2 Coordinates Converter

Press main menu Tools → Coordinates Converter to enter Coordinates Converter:



6.2.1 Convert a Single Point

To convert a single point, do the following:

- 1. Select a type of the source coordinate:
 - o **BLH**: including latitude, longitude and altitude.
 - o **XYZ**: the geocentric coordinate, including X, Y, and Z.
 - NEZ: including northing, easting and elevation.
- 2. To set the source coordinate, do one of the following:
 - To use the current GPS coordinates, press , set antenna parameters and a point name.
 - To select a point from the point database, press and select the target point.
 - o To manually input coordinates, set values of coordinates.



- 3. To select a type of the target coordinate:
 - o BLH
 - XYZ
 - o **NEZ**
- 4. Press **Transform**. The result automatically shows in **Target Coordinate** area.
- 5. **Optional:** To save the converted coordinates as a new point to the point database, press **Save**, and input a point name.

6.2.2 Convert a File

To convert a file, do the following:

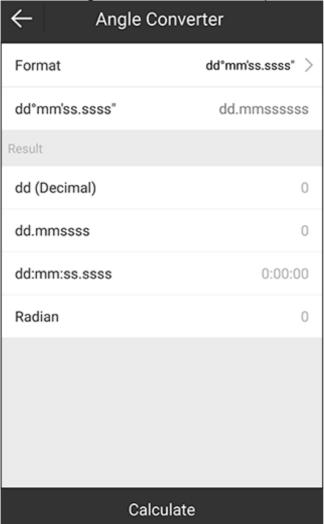
- 1. Select a type of the source coordinate:
 - o **BLH**
 - o **XYZ**
 - o NEZ
- 2. To select the format for the file to import, press **File**, do one of the following, and press **OK**:
 - Set file format, angle format and select whether to preview the file.
 - o Press Format Manager and customize a file format.
- 3. Select the target storage path.
- 4. select a type of the target coordinate:
 - o BLH
 - \circ XYZ
 - o NEZ
- 5. Press Transform.
- 6. To select a format for the file to export, do one of the following:
 - o Check the file format, and press **OK**.
 - o Press Format Manager and customize a file format.
- 7. Select the target storage path.



6.3 Angle Converter

To start angle conversion, do the following:

1. To enter **Angle Converter** interface, press main menu **Tools** → **Angle Converter**:



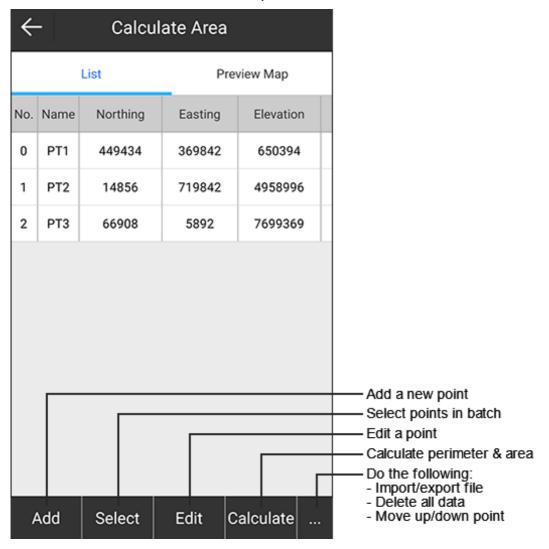
- 2. To select an angle format, press **Format**, and select one of the following:
 - dd(Decimal)
 - o dd.mmssss
 - o dd:mm:ss.ssss
 - o dd:mm:ss.ssss"
 - o Radian
- 3. Input an angle.
- 4. Press Calculate. The result shows in Result area.



6.4 Perimeter and Area

It is used to calculate perimeter and area of the graph formed by added points. At least 3 points that are not in a line are required.

To enter Calculate Area interface, press main menu Tools → Perimeter and Area:

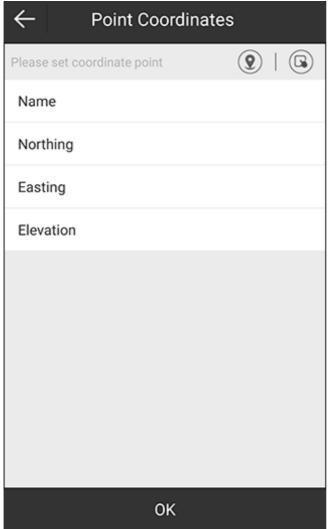




6.4.1 Add a New Point

To add a new point, do the following:

1. Press Add. Point Coordinates interface shows:



- 2. To set coordinates of the point, do one of the following:
 - To use the current GPS coordinates, press , set antenna parameters and a point name.
 - To select a point from the point database, press and select the target point.
 Alternatively, you can press Select in Calculate Area interface, and select a point from the point database.
 - To manually input coordinates, set values of Northing, Easting and Elevation.
- 3. Press OK.

6.4.2 Edit a Point

To edit a point, do the following:

- 1. Select the target point, and press **Edit**.
- 2. Edit name and coordinates of this point.



6.4.3 Calculate Perimeter and Area

To calculate perimeter and area, press **Calculate**. The result shows:

Result

Area:146024381550.000000m²
Area:14602438.155000ha
Perimeter:1801841.273m

OK

6.5 COGO Calculation

It is used to calculate distances, azimuths, point positions and other coordinate geometry (COGO) functions by the following methods:

Method		Known information	Calculate	
Coordinate inverse calculation	N B	A, B	AB(2D), azimuth $A \rightarrow B(\alpha)$, elevation difference, ratio of slope, slope angle, and AB (3D)	
Point line calculation	P B A	A, B, C	AC(2D), BC(2D), AP(2D), BP(2D), PC(2D), α, β	
Great-circle distance	A PB	Latitude, longitude and altitude for point A and B	Great-circle distance of AB	
Two lines angle	O B	A, B, O	Clockwise angle α	
Intersection calculation	B D C	A and B (on 1st straight line), C and D (on 2nd straight line)		
Resection	L1 L2 B	A, B, L1, L2	Р	
Forward intersection	A α β B	Α, Β, α, β	Р	



Method		Known information	Calculate	
Coordinate positive calculation	B α P	Α, Β, L1, α	Р	
Offset point calculation	C L2 A L1 P B	A, B, L1, L2	С	
Equal point calculation	A n	A, B (AB is divided into multiple parts by certain distance.)	Each divided points	

To start COGO calculation, do the following:

- To enter COGO Calculation interface, press main menu Tools → COGO Calculation.
- 2. Select the target method.
- 3. To set coordinates of points, do one of the following:
 - To use the current GPS coordinates, press , set antenna parameters and a point name.
 - To select a point from the point database, press and select the target point.
 - o To manually input coordinates, set values of **Northing**, **Easting** and **Elevation**.
- 4. Press Calculate. The result shows in Result area.



6.6 Calculator

It is used for the convenience of some simple data calculation.

To use the calculator, press main menu **Tools** \rightarrow **Calculator** to enter **Calculator** interface:





6.7 External Radio Configuration

Before setting external radio configuration, make sure the receiver is disconnected.

To set external radio configuration, do the following:

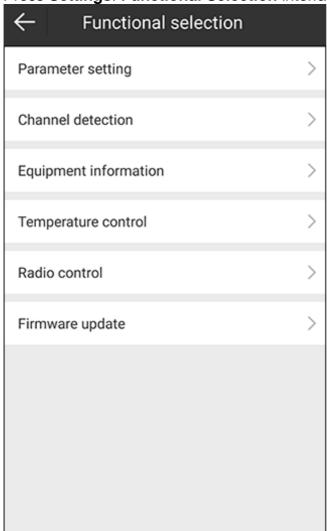
 To enter Radio Mode interface, press main menu Tools → External Radio Configuration:

← Radio Mode			
Radio type	Geoelectron >		
Connection mode	Bluetooth >		
Search bluetooth device list			
E600351800033	0C:AE:7D:C8:2D:0C		
E5003A20000217	74:7A:90:38:8E:0B		
E30P3A2000089	D4:53:83:61:04:FE		
E5003A20000223	74:7A:90:3B:05:66		
TRU3038100006	BF:18:18:11:5F:CC		
E30P3A1900047	D4:53:83:5F:8F:F1		
E5003A20000038	74:7A:90:37:EF:67		
Search	Connect		

- 2. Select a radio type, and connection mode.
- 3. Press **Search**. SurPad automatically searches all devices with Bluetooth on.
- 4. Select the target device, and press **Connect**. **Search** button turns into **Settings** button when the connection succeeds.

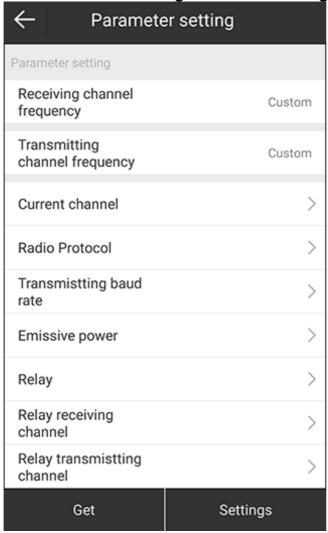


5. Press **Settings**. **Functional Selection** interface shows:



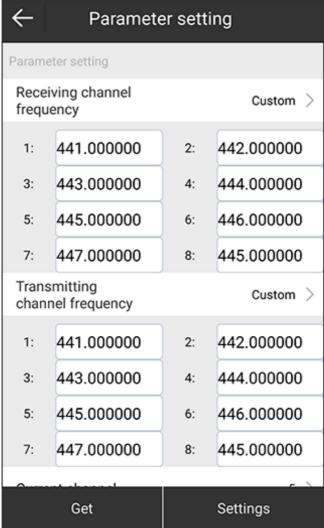


- 6. To finish parameter settings, do the following:
 - a. Press Parameter setting. Parameter setting interface shows:





b. To obtain parameters of the current connected external radio, press **Get**:



- c. After the configuration is set, press **Settings**.
- d. Optional: Customize parameters of the current external radio.

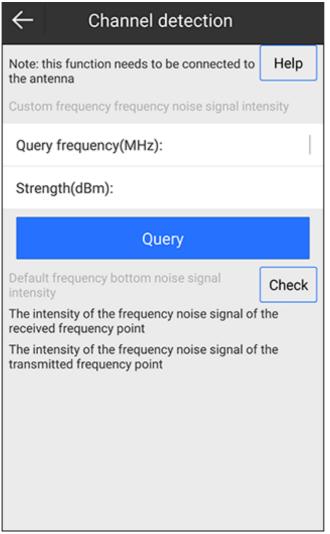


7. To start a channel test, do the following:



CAUTION: an external radio antenna is required.

a. Press Channel detection. Channel Detection interface shows:



- b. Optional: To check help information, press Help.
 - Signal is stronger: ≥ -95 dBm
 - Signal is weak: -105 dBm ~ -95 dBm
 - Signal is very weak (no signal): ≤ -105dBm

Signal is stronger indicates that the channel is in use. It is suggested to skip the channel and use channels that are in range **Signal is very weak** (no signal).

c. Input the query frequency, and press **Query**. If the strength shows weak, it indicates that the channel is accessible.



d. To acquire the intensity of the frequency noise signal of the received and transmitted frequency point, press **Check**:



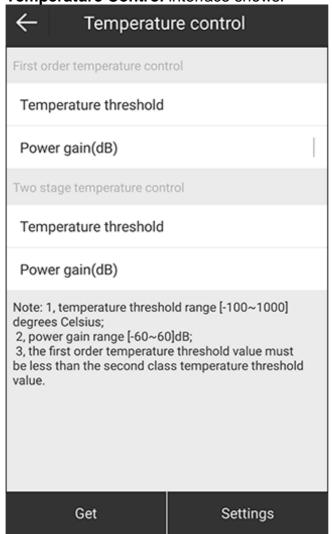


8. To check the equipment information, press **Equipment information** in **Functional Selection** interface, and press **Get** in **Equipment Information** interface. SurPad automatically gets equipment information:

Equipment information		
Equipment information		
Device serial number	TRU3038100006	
BOOT version	v1.13	
APP firmware version	1.1.0	
Board	TRU35_MB	
Board version	V1.1	
Radio module	TRM100	
Bluetooth	B102	
Temperature(°C)	32.2	
Voltage(V)	9.74	
Data of manufactura	2010.00.05	
Get		



- 9. To set temperature control, do the following:
 - a. Press **Temperature control** in **Functional Selection** interface. **Temperature Control** interface shows:



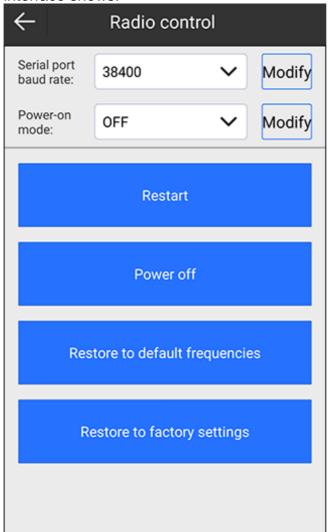
- b. To view temperature control of the current connected external radio, press **Get**.
- c. **Optional:** Customize temperature control of the current external radio.
 - Temperature threshold range: -100 °C ~1000 °C.
 - Power gain: -60 dB ~ 60 dB.

WARNING: The temperature threshold of the first order should be smaller than that of two stage.

d. Press **Settings** for saving temperature control.



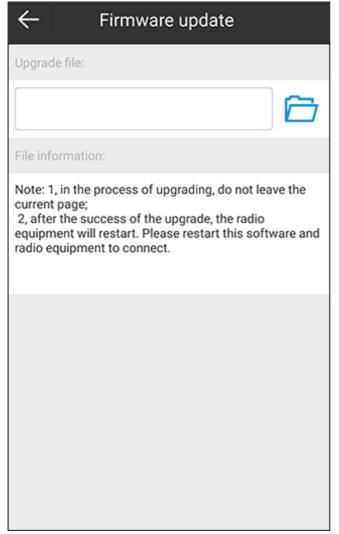
- 10. To set radio control, do the following:
 - a. Press Radio control in Functional Selection interface. Radio Control interface shows:



- b. To change the serial port baud rate, select baud and press **Modify**.
- c. To select whether to enable power-on mode, select a selection and press **Modify**.
- d. Do one of the following based on your own needs:
 - To restart the external radio, press Restart.
 - To power off the external radio, press Power off.
 - To restore the changed frequency to its default settings, press
 Restore to default frequencies.
 - To eliminate all user-defined information for the external radio, press Restore to factory settings.



11. To update firmware, press **Firmware update** in **Functional Selection** interface, and select a firmware file with *.bin format in **Firmware Update** interface:



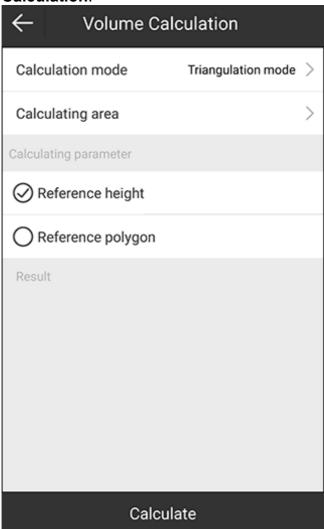


6.8 Volume Calculation

It is used for land levelling, roadbed excavation, excavation for civil air defense projects, ground filling, roadbed filling and pit backfilling with small-scale, high-precision landform.

To start volume calculation, do the following:

To enter Volume Calculation interface, press main menu Tools → Volume Calculation:



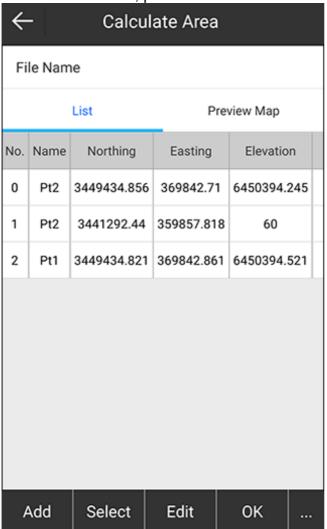


2. To enter Polygon Database interface, press Calculating area:





3. To add a new area, press **New**:



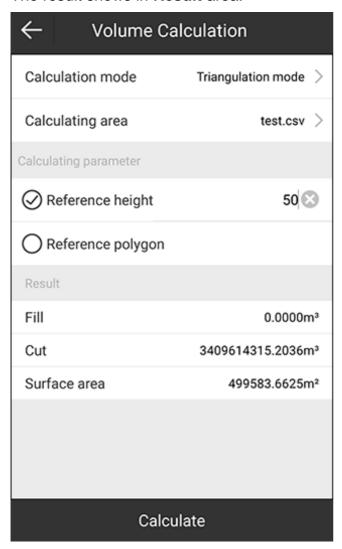
- 4. Set a file name.
- 5. To get coordinates of points, do one of the following, and press **OK**:
 - To obtain the current GPS data, select from the point database, or manually set coordinates, press Add, and do related operations.
 - To select points from the point database in batch mode, press Select, and select the target points.
 - To directly import a file (*.dat, *.csv, *.txt), press ... → Import and select the target file.

The interface returns to **Polygon Database** interface.

- 6. Select the target polygon, and press **OK**. The interface returns to **Volume Calculation** interface.
- 7. To select a way to calculate the set area, do one of the following:
 - Set the reference height, and press Calculate.
 - Press Reference polygon, and select the target polygon in polygon database, and press Calculate.



The result shows in **Result** area:





6.9 Add Offsets to Points at Specified Period

It is usually used when data is collected without localization and it needs to calibrate data of a certain period after collection.

To add offsets to points at specified period, do the following:

- To enter Add Offsets to Points at Specified Period interface, press main menu Tools → Add Offsets to Points at Specified Period.
- 2. To calculate the localization parameters, press **Marker Point Calibration**, set coordinates of the known point and the current WGS84 coordinates, and press **Calculate**. The result shows:

Calculate. The result shows: Add offsets to points at specified period			
Marker Point Calibratio	n >		
dX	-0.032		
dY	0.151		
dH	0.088		
Clear	Update		



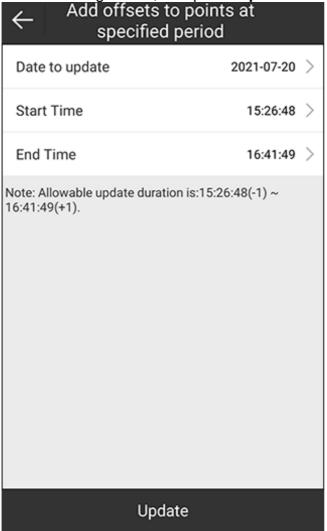
3. Press **Update**. The following interface shows:

Add offsets to points at specified period			
Base ID	Start Time	Base_B	
1003	2021-07-20 15:26:48.000	N31°05'03.893"	E12
Update			



4. Select the target data, and press **Update**. The following interface shows:

Add offsets to points at



5. To calibrate date of a certain period, set the data to update, start time and end time, and press **Update**.



6.10 FTP Shared Data

It is used to share data between SurPad and your PC in real time through FTP.

Before sharing data through FTP, make sure SurPad and your PC are in the same local area network.

To share data through FTP, do the following:

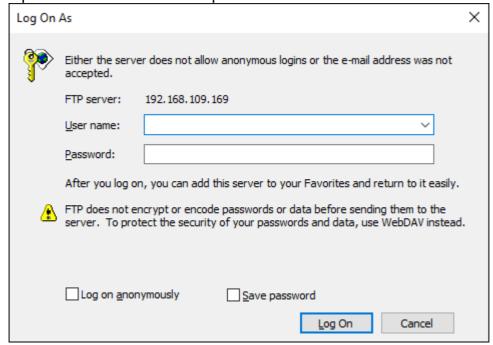
1. To enter FTP Shared Data interface, press main menu Tools → FTP Shared Data:



- 2. Select the target path.
- 3. Set user name and password.
- 4. Set port. The FTP address changes in real time.
- 5. To save settings, press **Open**.
- 6. Input the FTP address into the address bar of your PC:



7. Input the set user name and password to access:



8. Start sharing files.

6.11 Share

It is used to share files in both device memory and SurPad memory to other Apps in your device.

The Apps that can be shared depend on the software you have installed, and SurPad 4. 2 is only responsible for calling the Android interface.

To share files, do the following:

- 1. Press main menu **Tools** → **Share**.
- 2. Select the target file in the target directory, and press **OK**.
- 3. Select the target App in your device.

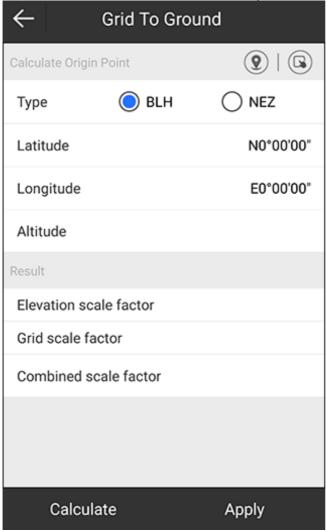


6.12 Grid to Ground

It is used to calculate the scale factor between the total station and RTK in high attitude area, so as to achieve coordinate conversion.

To start grid to ground, do the following:

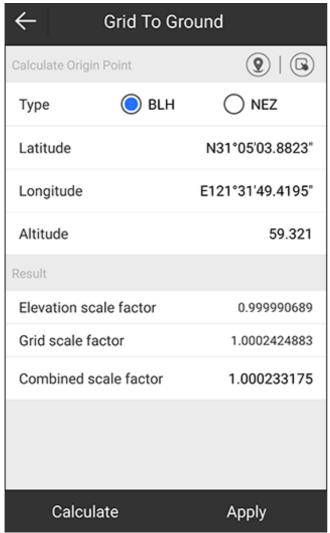
1. To enter **Grid to Ground** interface, press main menu **Tools** → **Grid to Ground**:



- 2. Select a type of the source coordinate:
 - o **BLH**: including latitude, longitude and altitude.
 - NEZ: including northing, easting and elevation.
- 3. To set coordinates of a point, do one of the following:
 - To use the current GPS coordinates, press , set antenna parameters and a point name.
 - To select a point from the point database, press and select the target point.
 - To manually input coordinates, set values of Latitude, Longitude and Altitude, or Northing, Easting and Elevation.



4. Press Calculate. The result shows in Result area:



5. To apply the result, press **Apply**.



To view the calculated ground coordinates, press main menu $\mathbf{Project} \to \mathbf{Points}$ **Database**, and select the target point, and press **Details**:

← Point De	Point Details		
Title	Content		
Easting	369854.219		
Elevation	0.8		
x	-2859097.112		
Υ	4660052.211		
z	3273938.437		
Туре	Survey Point		
Combined Factor	1.0002330914		
Ground N	3449427.287		
Ground E	369854.217		
Ground H	0.8		
Record Mode	Topo Point		
Photo And Sketch			



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